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Gaussian process regression method for forecasting of mortality rates

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Existing models in literature for forecasting mortality rates

• Lee-Carter model (1992), Lee-Miller model (2001)

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• Hyndman-Ullah model (2007)

Our Gaussian process regression (GPR) model

 Consider the mortality curve of a specific age group over time to follow a Gaussian process

Predictive results of different age groups converted into complete mortality-over-age picture of a future year using interpolation

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Fundamentals of Gaussian process regression

- Definition: Gaussian process is a stochastic process that any finite subset throughout its domain follows a multivariate normal distribution, a less parametric tool
- A nonlinear regression model with noise:

 $y = f(x) + \varepsilon, \varepsilon \sim N(0, \sigma^2)$

A mean function μ(·) and a covariance function k(·,·) defined for f(x)



Fundamentals of Gaussian process regression

The covariance function (kernel function) is defined as:

 $Cov(f(x), f(x')) = k(x, x'; \theta),$

where θ denotes the set of hyper-parameters, estimated by empirical Bayesian approach

Gaussian process regression (GPR) model can then be denoted as: Enterprise and rie

 $f(x) \stackrel{\text{(}}{\sim} GPR[\mu(\cdot), k(x, x'; \theta) | x]. \quad \text{(} u^{\text{(}} \mu^{\text{(}} \mu^{($

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Fundamentals of Gaussian process regression

• Given observed data $\mathcal{D} = \{(x_1, y_1), \dots, (x_n, y_n)\},\$

$$\Psi_{ij} = Cov(y_i, y_j) = k(x_i, x_j; \theta) + \sigma^2 \delta_{ij},$$

- $\hat{\theta}$ and $\hat{\sigma}$ calculated by maximizing the marginal log-likelihood
- For a new input x*, E(f(x*)|D) = μ(x*) + ψ^T(x*)Ψ⁻¹(y − μ), Var(f(x*)|D) = k(x*, x*; θ) − ψ^T(x*)Ψ⁻¹ψ(x*).
 ŷ* = E(y*|D) = E(f(x*)|D), ô*² = Var(y*|D) = Var(f(x*)|D) + ô²

95% confidence interval: $(\hat{y}^* - 1.96\hat{\sigma}^{*2}, \hat{y}^* + 1.96\hat{\sigma}^{*2})$



GPR models in forecasting mortality rates

- Let $y_x(t)$ denote log of mortality rate for age x in year t
- Underlying function $f_x(t)$ observed with error at discrete points
- $y_x(t_i) = f_x(t_i) + \varepsilon_{i,x}, x = 1, ..., n, i = 1, ..., m$
- Forecast $y_x(t)$ for $t \in [t_{m+1}, t_{m+h}]$





Basic GPR models

- Mean function: use a linear function obtained from smoothing the past observed data by linear regression.
- Covariance function: squared exponential (SE), Matern (MA), rational quadratic (RQ)

•
$$k_{SE}(\tau) = \sigma^2 \left(-\frac{\tau^2}{2l^2} \right),$$

$$k_{MA}(\tau) = \sigma^2 \left(1 + \frac{\sqrt{3}}{l} \tau \right) exp \left(-\frac{\sqrt{3}}{l} \tau \right),$$

$$k_{RQ}(\tau) = \sigma^2 \left(1 + \frac{\tau^2}{2\alpha l^2} \right)^{-\alpha}.$$
where $\tau = t - t'.$



Modified GPR model – with weighted mean function

- Extrapolation tends to move to prior mean in the long run.
- Previously model the mean function using equally weighted linear regression.
- Makes sense to use weighted least squares (WLS) to obtain mean function

• Parameters chosen to minimize $e = \sum_{i=1}^{m} z_i (y_i - \hat{y}_i)^2$, where $z_i = 1/(t_0 - t_i)$ $z_i = 1/(t_0 - t_i)$ $z_i = 1/(t_$



Modified GPR model – with spectral mixture kernels

- Adopt an idea raised by Wilson & Adam (2013): introduces simple closed form kernels derived by modelling a spectral density with a Gaussian mixture.
- $k(\tau) = \int_{R^P} e^{2\pi i s^T \tau} \varphi(ds), \varphi$ is a positive finite measure, has density S(s)

•
$$k(\tau) = \int_{R^P} S(s) e^{2\pi i s^T \tau} ds$$
, $S(s) = \int_{R^P} k(\tau) e^{-2\pi i s^T \tau} d\tau$.

 Wilson and Adam (2013): any stationary covariance kernels can be approximated to arbitrary precision using mixture of Gaussians in spectral density.

Model S(s) to be mixture of Gaussian, extend to P dimensions.
 22 October 2015



Applications of GPR models in forecasting French mortality rates

- Quote French total mortality data from Human Mortality Database (HMD)
- Data from 1950-2010: 1950-1990 as training data, 1991-2010 as testing data
- Basic GPR models, using SE, MA and RQ as kernels

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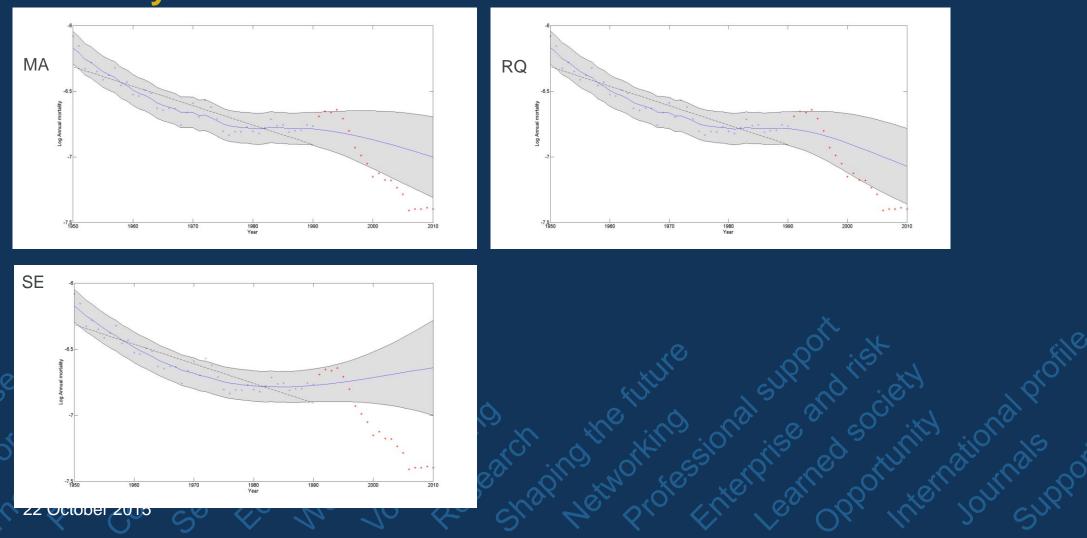
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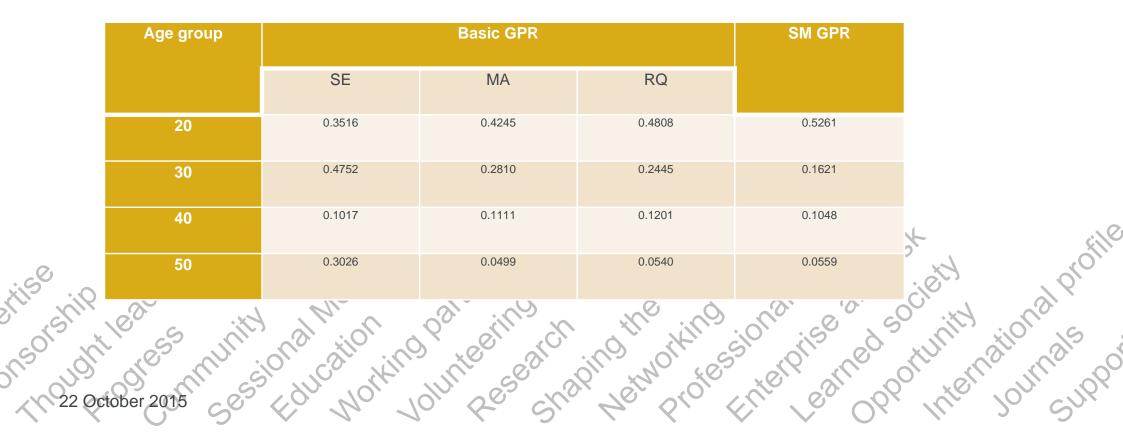
Applications of GPR models in forecasting French mortality rates – Basic GPR models





Basic GPR models & SM GPR models

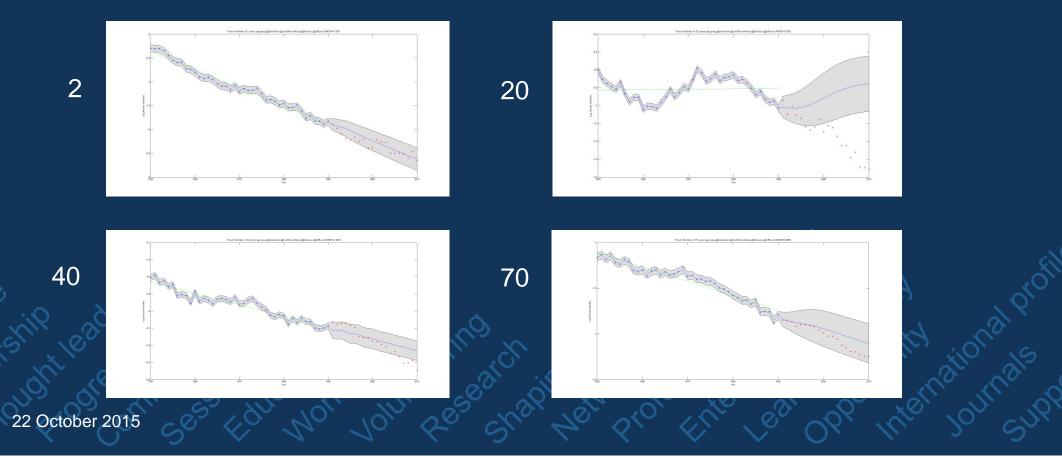
• Table 1.Record of RMSE of French log mortality of 20, 30, 40 and 50 years group using SE, MA, RQ and SM kernels respectively





GPR model with spectral mixture (SM) kernel

Pick out 17 specific age groups: 0, 1, 2, 5, 10, 12, 15, 18, 20, 30, 40, 50, 60, 70, 80, 90, 100 years group





GPR model with spectral mixture (SM) kernel and weighted mean function

	Age group	SM GPR	SM GPR with weighted mean	Average PMSE
	0	0.1558	0.1324	Average RMSE
	1	0.4157	0.0930	SM GPR:0.2514
	2	0.1097	0.0993	
	5	0.4204	0.2058	SM GPR with weighted mean
	10	0.4566	0.3584	function:0.1713
	12	0.3182	0.2319	
	15	0.3625	0.2810	
	18	0.6495	0.3427	
	20	0.5261	0.3775	
	30	0.1621	0.3052	
	40	0.1043	0.0975	ist spint
. S	50	0.0559	0.0725	with all all all all all
	60	0.1211	0.0499	
de la	70	0.0883	0.0493	in is a so in it in is
2	80	0.1453	0.0742	on the the the the the
til ^{SO}	90	0.0619	0.0571	inture support isk and
	100	0.1200	0.0839	X, X, X, Q, Q, W, Z, Q

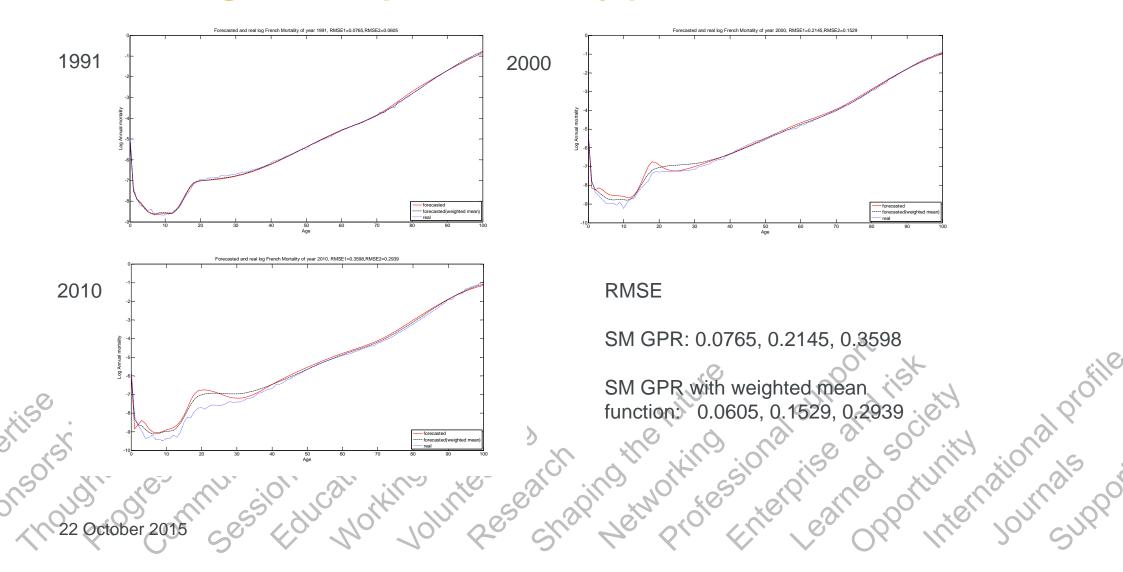


Generating the complete mortality picture

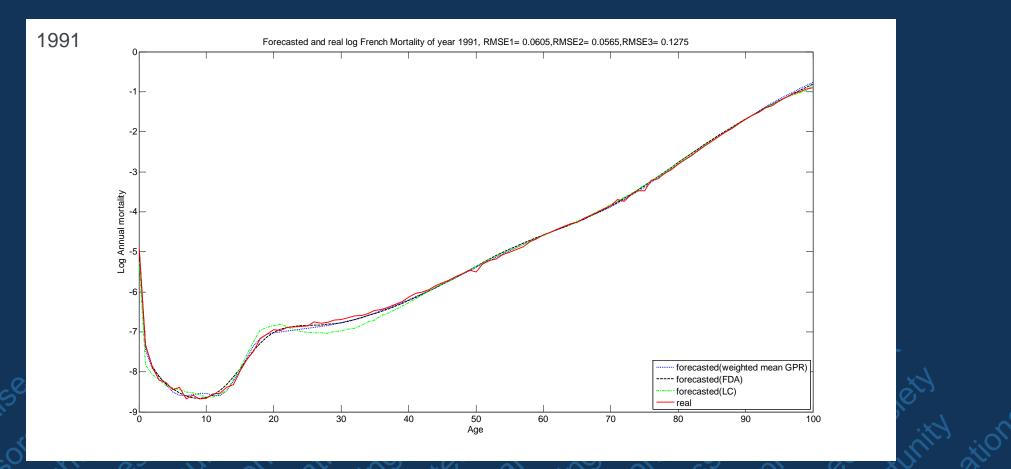
- 1991 (1-year horizon), 2000 (10-year horizon), 2010 (20-year horizon)
- Estimate log mortality of the 17 age groups for the three years, use splines for interpolation



Generating the complete mortality picture

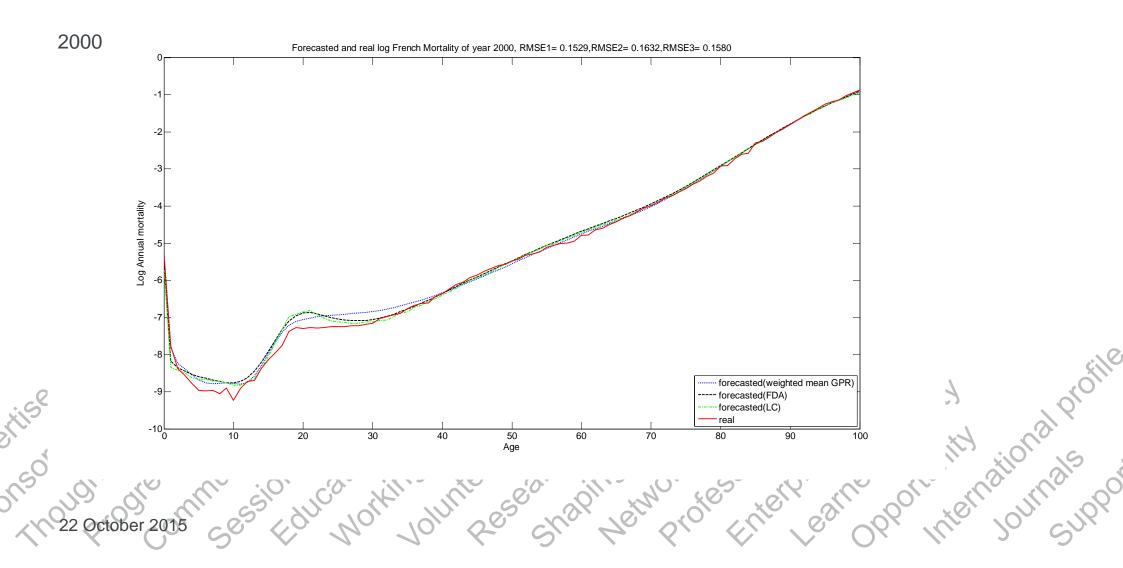




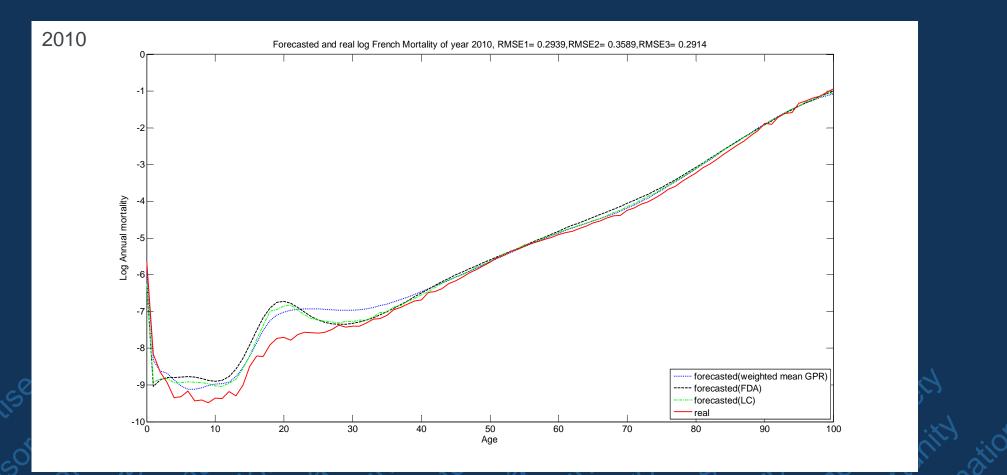


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RMSE

	1991	2000	2010
SM GPR WM	0.0605	0.1529	0.2939
FDA	0.0565	0.1632	0.3589
LC	0.1275	0.1580	0.2914







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