

Smoothing and Forecasting Mortality Rates with P-splines

Iain Currie
Heriot Watt University

London, June 2006

Data and problem

- Data: CMI assured lives
 - Age: 20 to 90
 - Year: 1947 to 2002

Data and problem

- Data: CMI assured lives
 - Age: 20 to 90
 - Year: 1947 to 2002
- Problem: forecast table to 2046

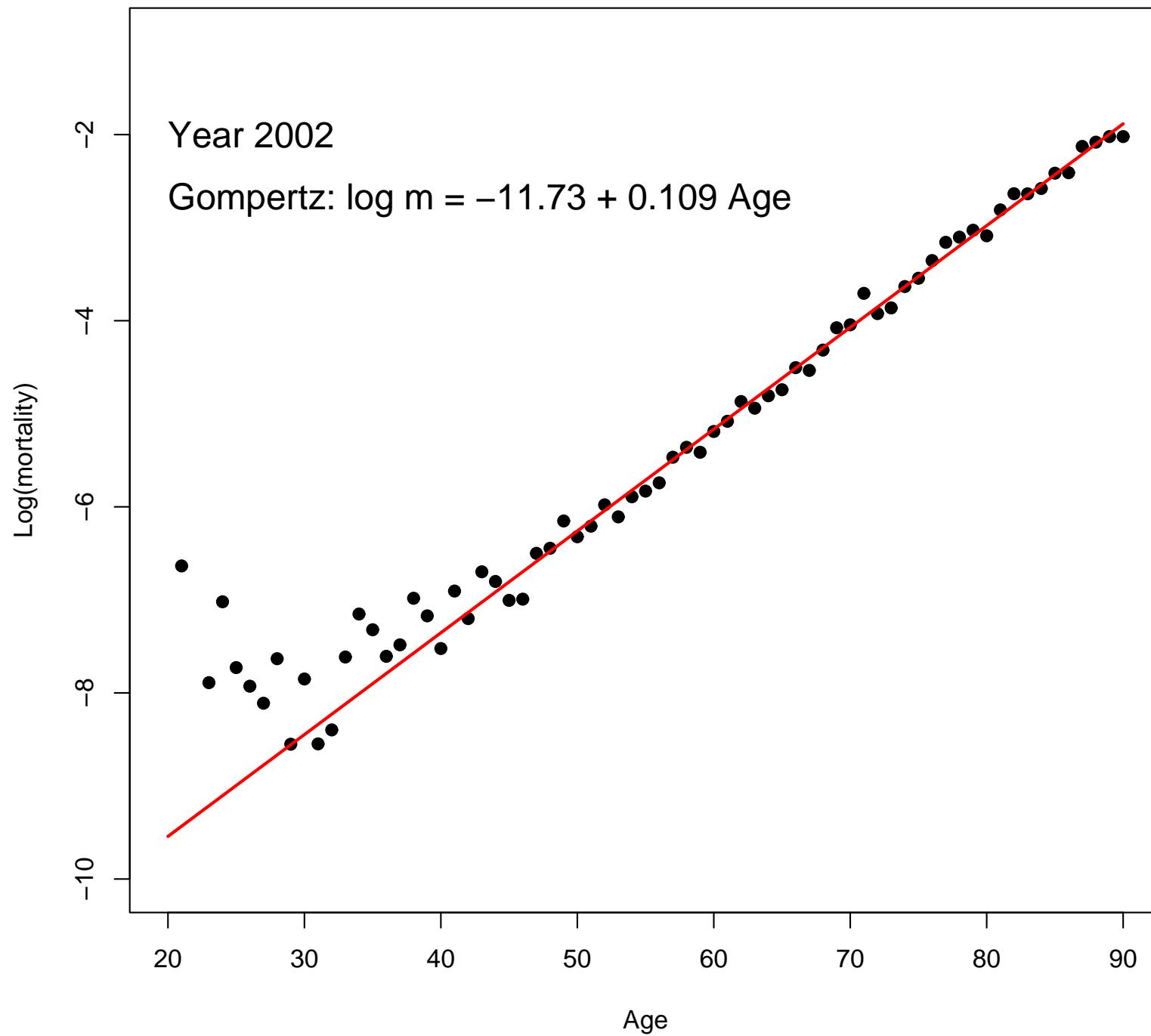
Plan of talk

- P-splines in 1-dimension

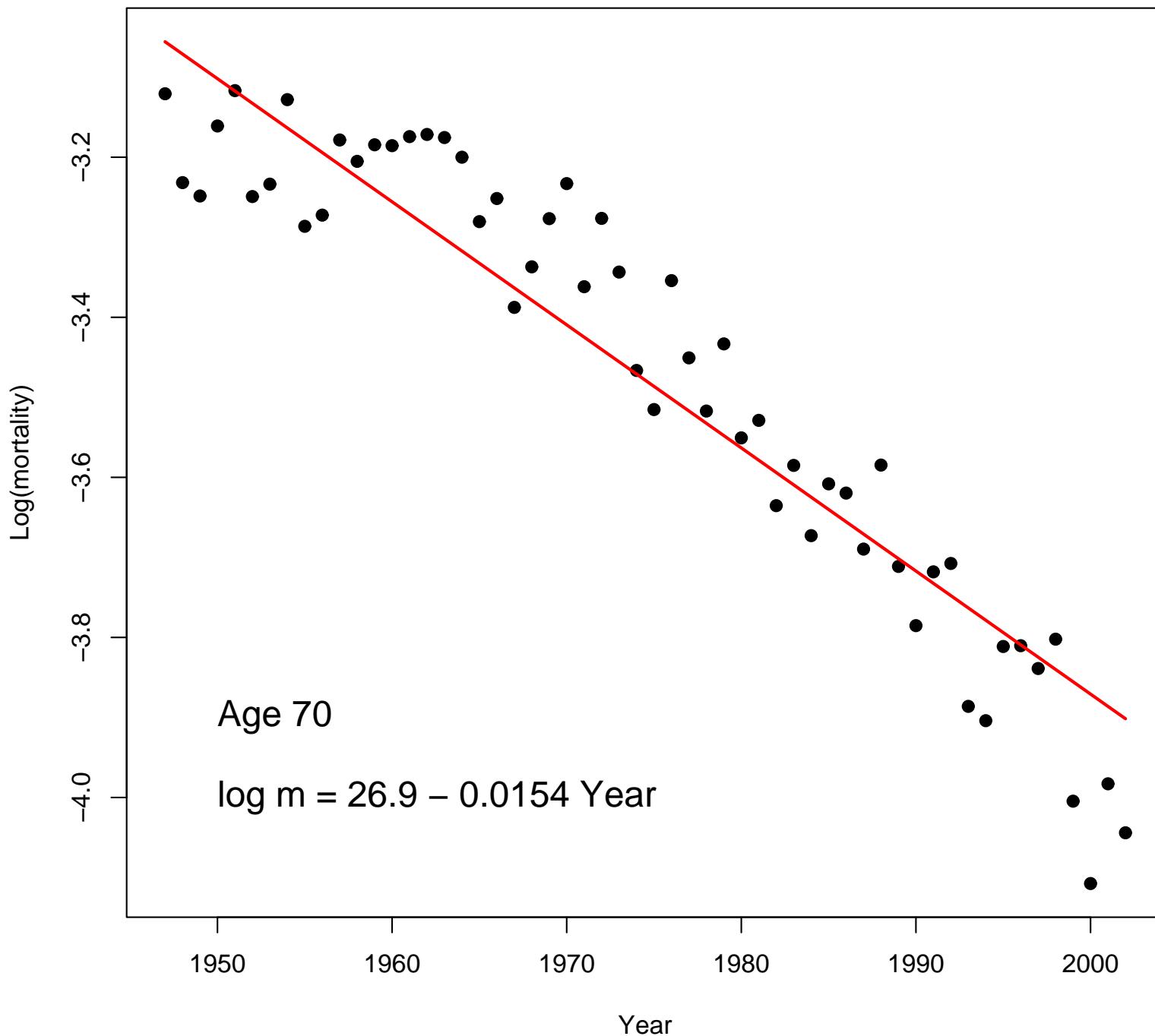
Plan of talk

- P-splines in 1-dimension
- P-splines in 2-dimensions
 - Lee-Carter model
 - Age-Period-Cohort model
 - 2-d P-splines

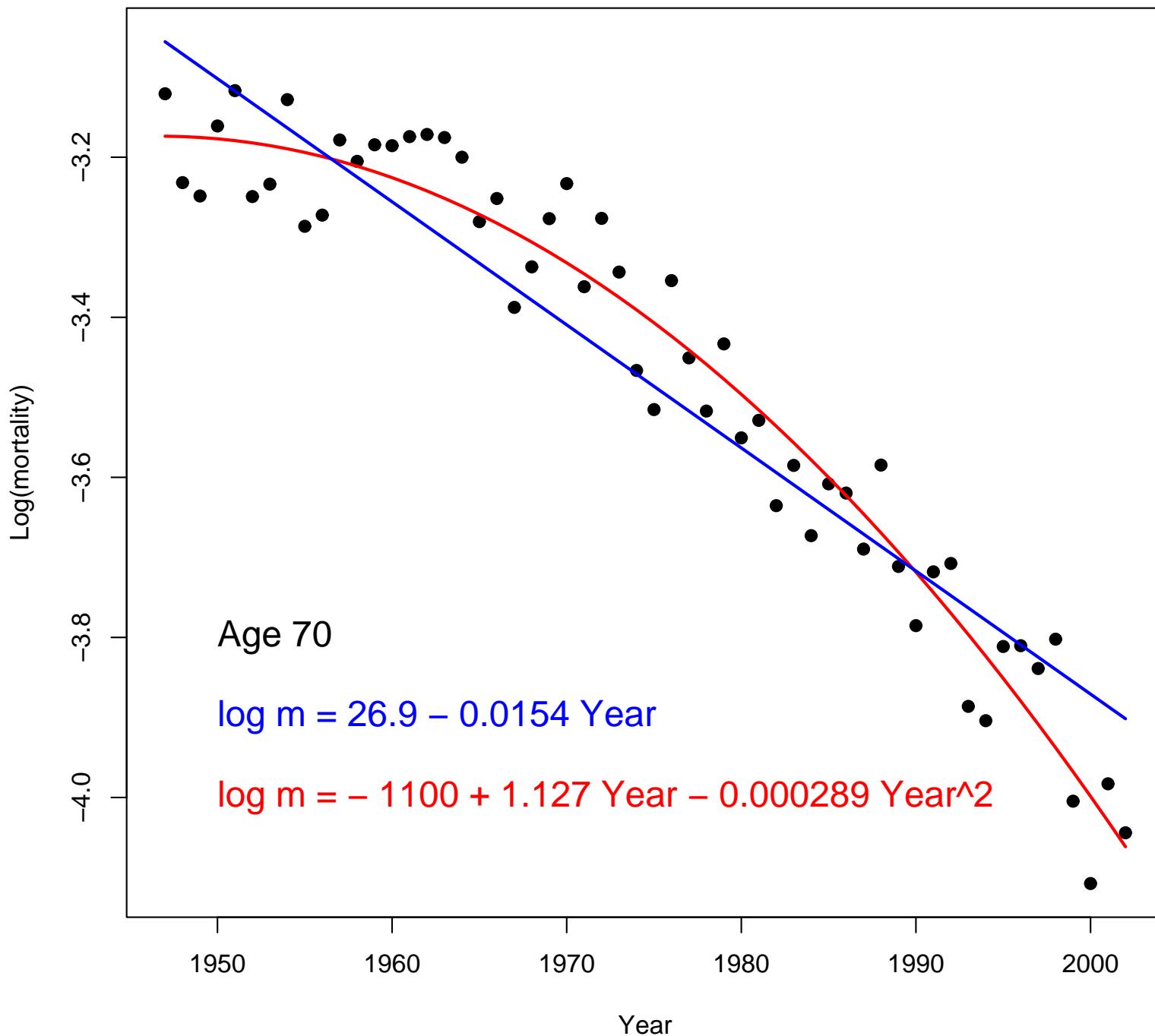
Gompertz model



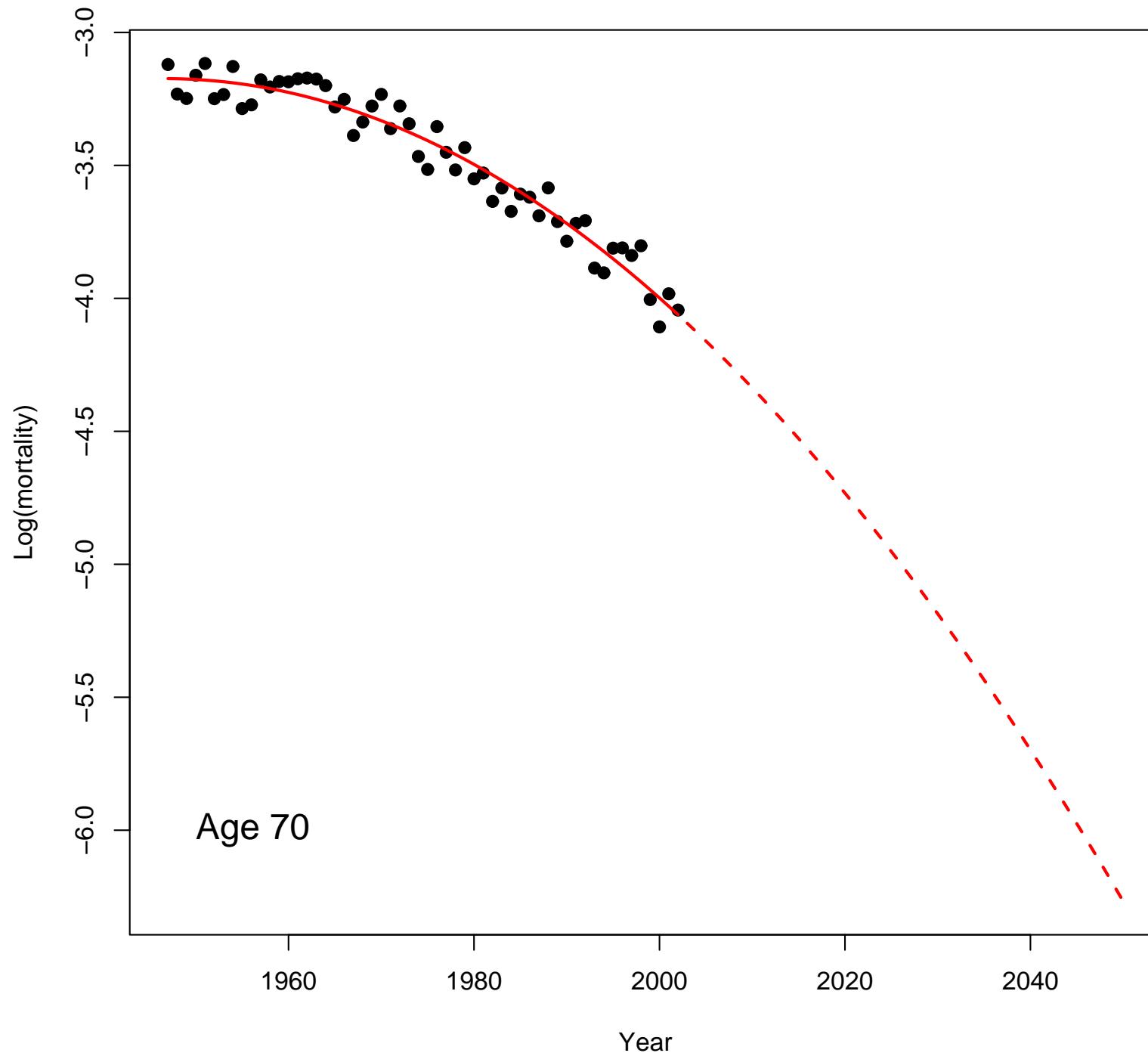
Simple Gompertz



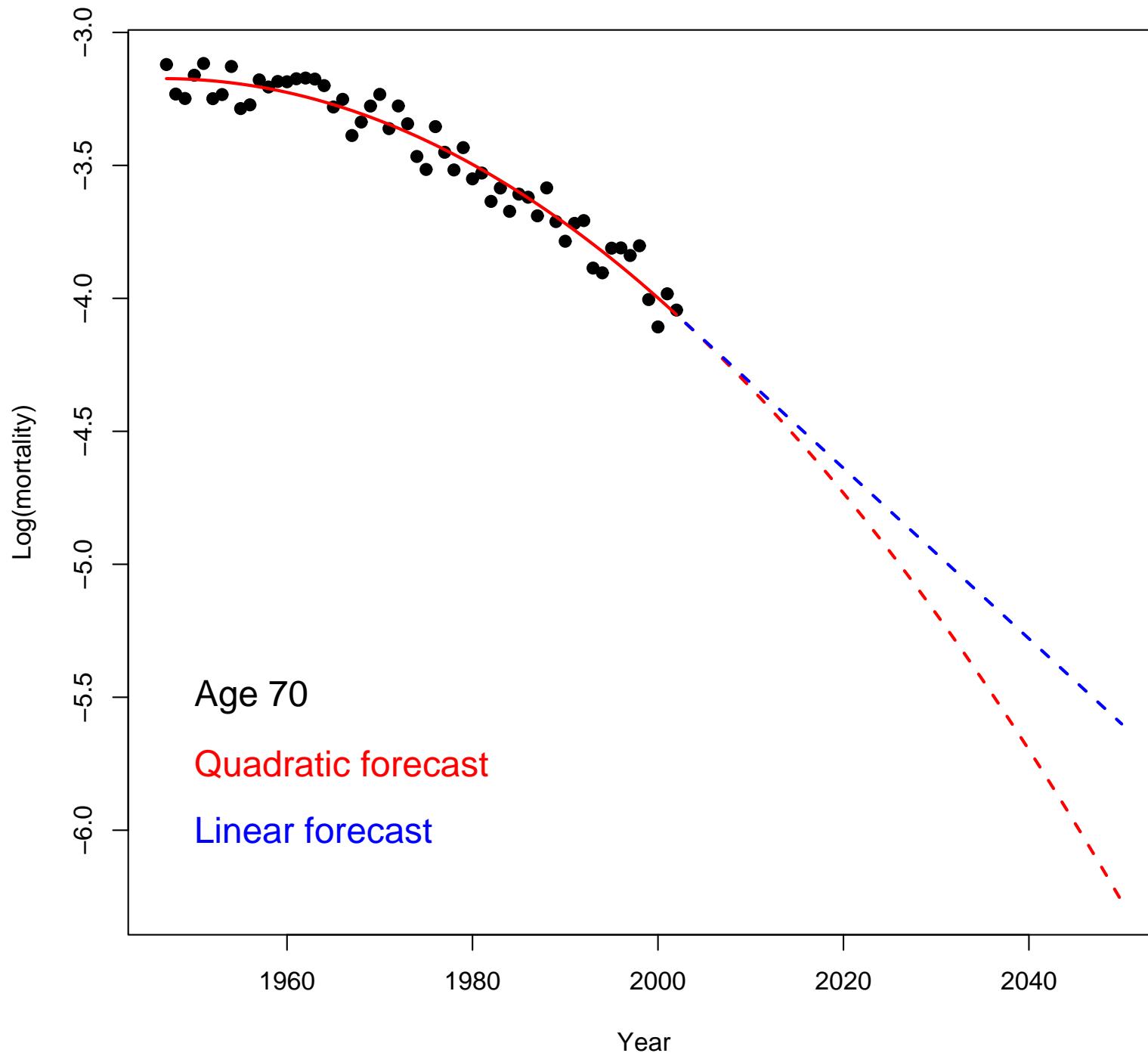
Quadratic Gompertz



Quadratic forecast



Quadratic fit: linear & quadratic forecasts



Regression basis

In ordinary regression we use basis like

$$\text{Linear basis: } \{1, x\}$$

$$\text{Quadratic basis: } \{1, x, x^2\}$$

$$\text{Polynomial basis: } \{1, x, x^2, \dots, x^p\}.$$

Regression basis

In ordinary regression we use basis like

$$\text{Linear basis: } \{1, x\}$$

$$\text{Quadratic basis: } \{1, x, x^2\}$$

$$\text{Polynomial basis: } \{1, x, x^2, \dots, x^p\}.$$

Means and fitted values are linear combinations of the basis functions

$$\log \mu = a + bx, \quad \log \hat{\mu} = \hat{a} + \hat{b}x$$

$$\log \mu = a + bx + cx^2, \quad \log \hat{\mu} = \hat{a} + \hat{b}x + \hat{c}x^2$$

$$\log \mu = a + b_1x + \dots + b_p x^p, \quad \log \hat{\mu} = \hat{a} + \hat{b}_1x + \dots + \hat{b}_p x^p$$

Generalised linear models

Model fitting uses the **Generalised Linear Model** framework.

$$d_x \sim \mathcal{P}(E_x^c \mu_x)$$

and $\log E_x^c \mu_x = \log E_x^c + a + bx$

or $\log E_x^c \mu_x = \log E_x^c + a + bx + cx^2$.

B-spline basis

A B-spline regression basis uses **local** basis functions.

B-spline basis: $\{B_1(x), B_2(x), \dots, B_p(x)\}$

where $B_1(x), B_2(x), \dots, B_p(x)$ are B-splines.

B-spline basis

A B-spline regression basis uses local basis functions.

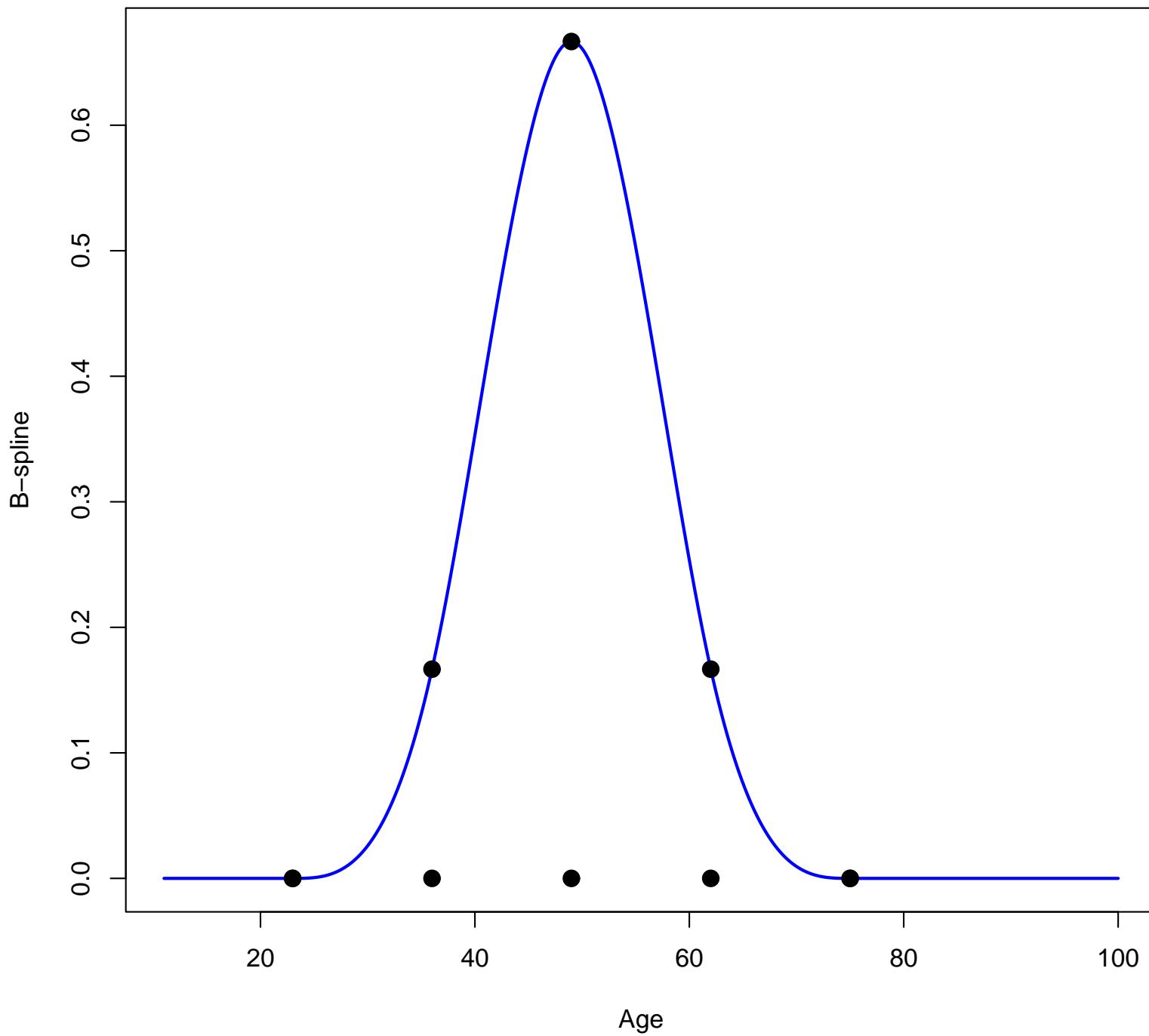
B-spline basis: $\{B_1(x), B_2(x), \dots, B_p(x)\}$

where $B_1(x), B_2(x), \dots, B_p(x)$ are B-splines.

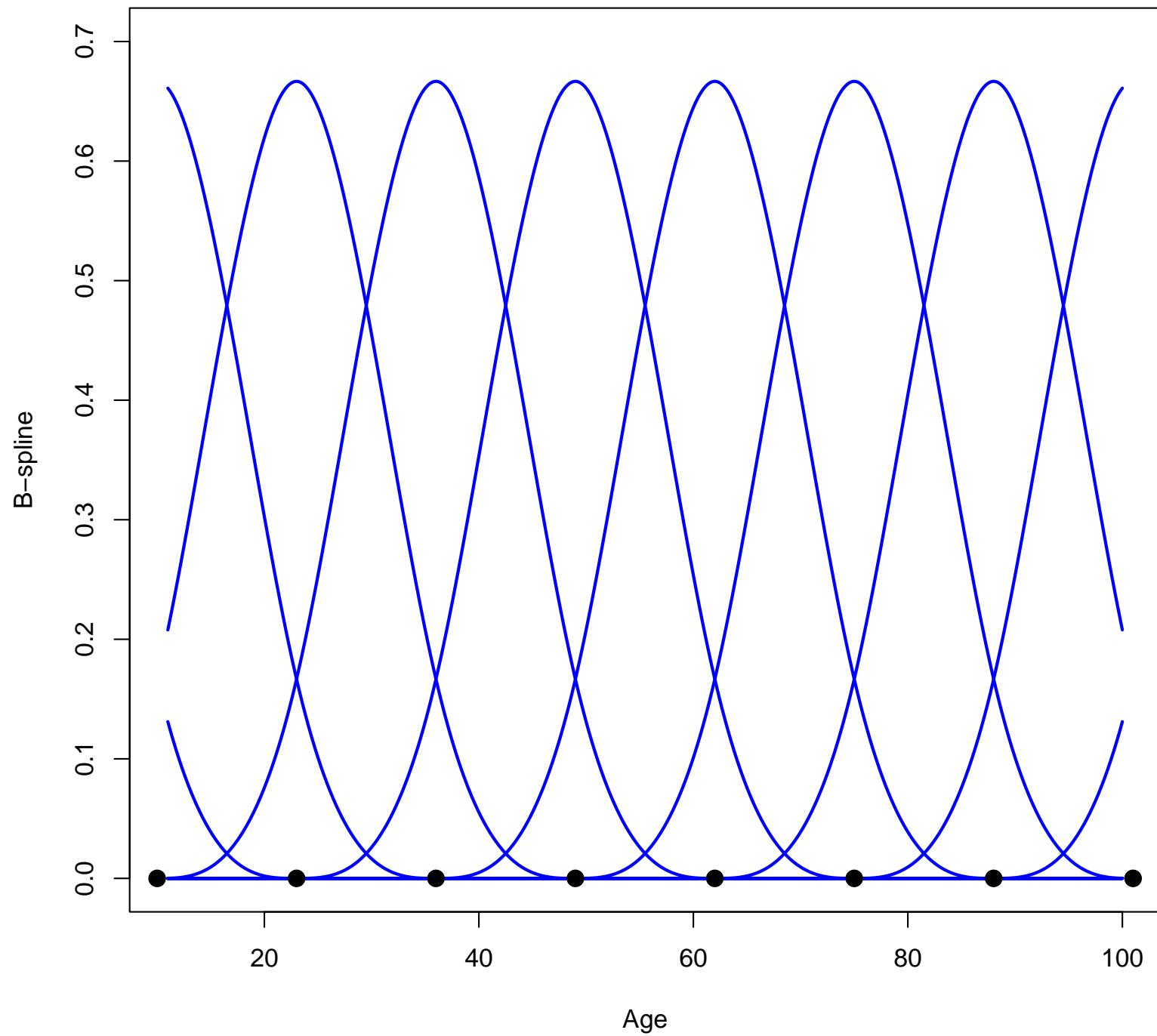
Means and fitted values work the same way

$$\log \mu = \sum_1^p \theta_j B_j(x), \quad \log \hat{\mu} = \sum_1^p \hat{\theta}_j B_j(x)$$

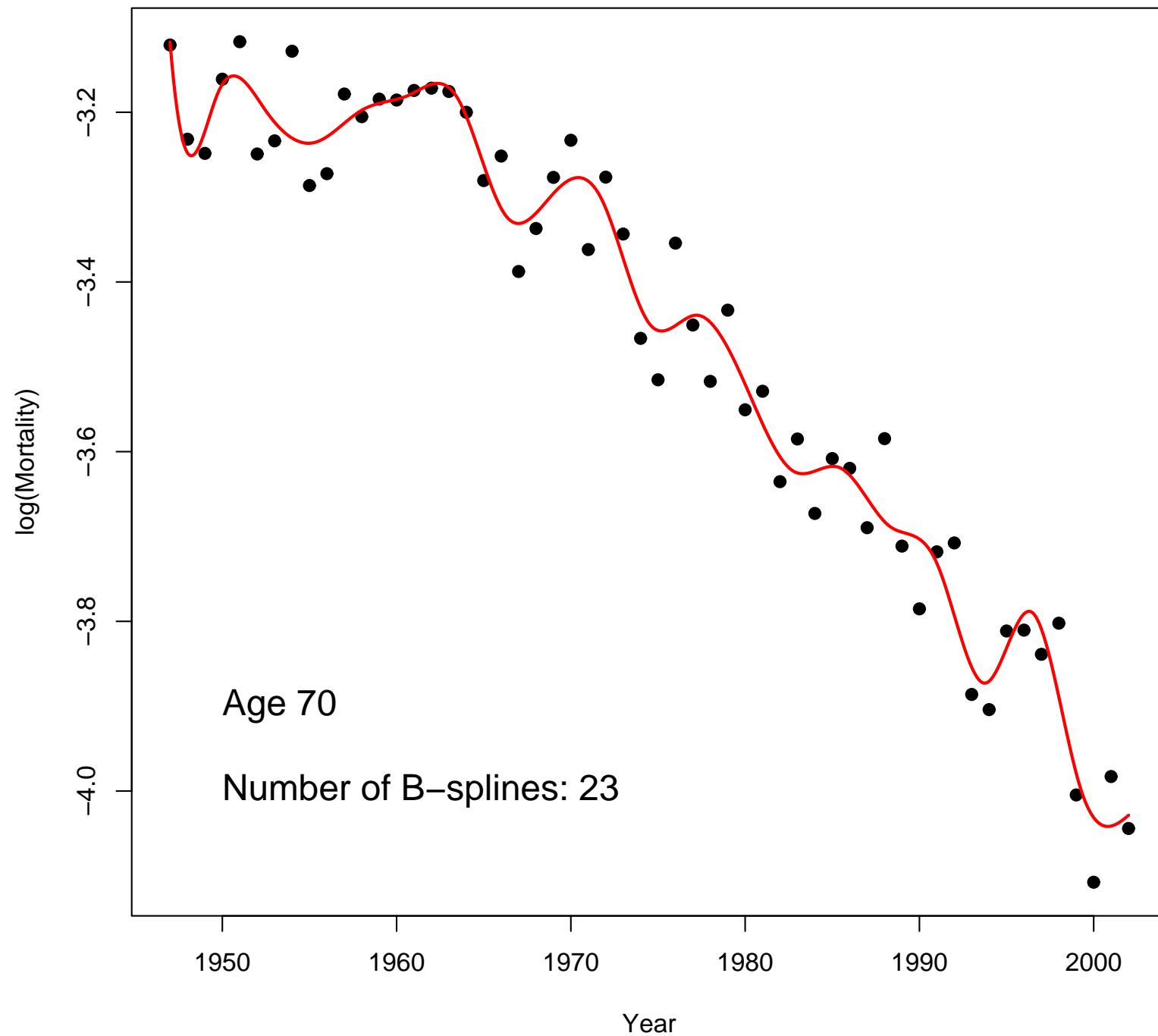
A single cubic B-spline



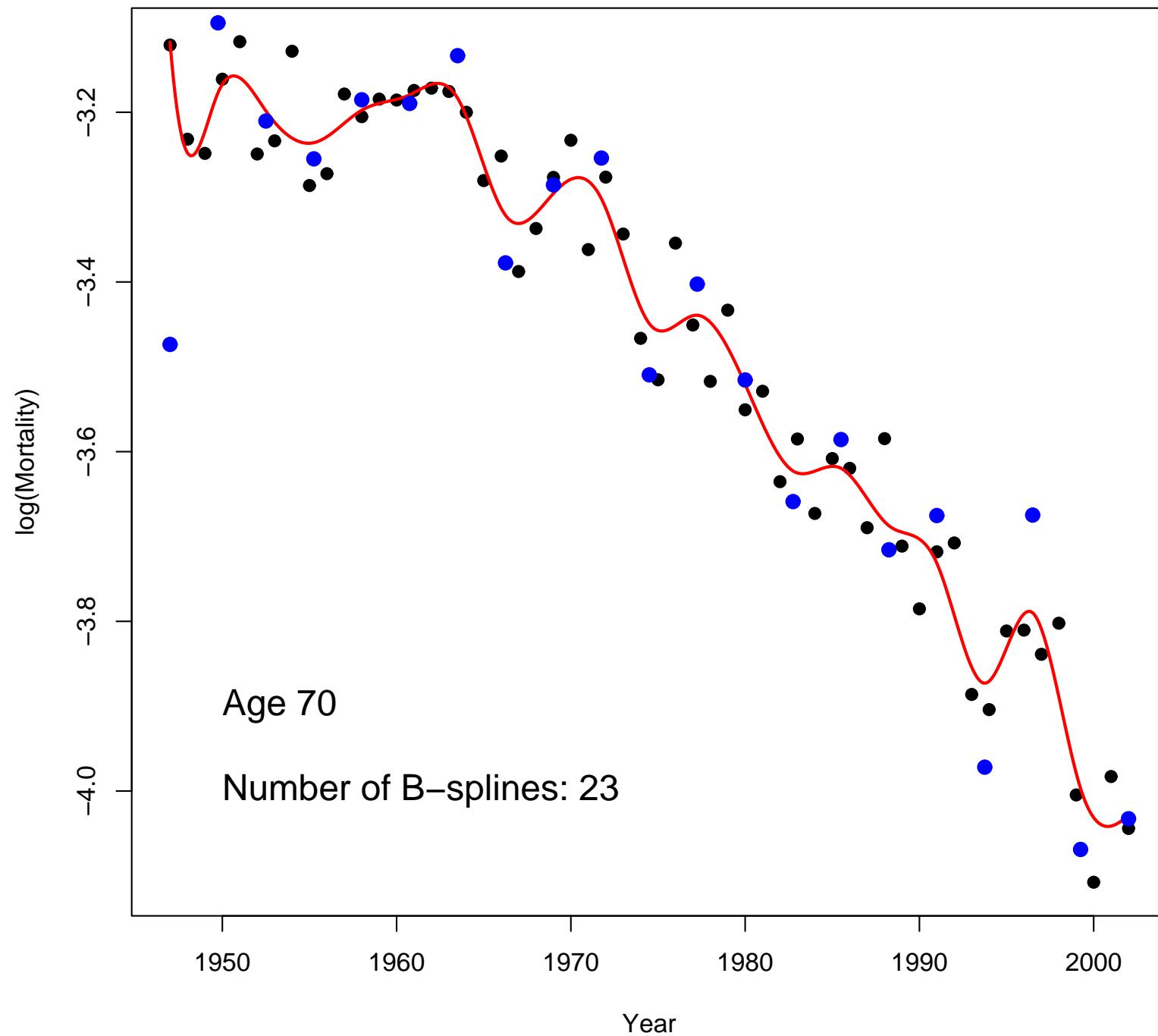
Cubic B-spline basis



B-spline regression



B-spline regression



Penalties

Eilers & Marx (1996) imposed **penalties** on **differences** between adjacent coefficients.

$$\begin{aligned} P_2(\theta) &= (\theta_1 - 2\theta_2 + \theta_3)^2 + \dots + (\theta_{p-2} - 2\theta_{p-1} + \theta_p)^2 \\ &= \theta' D_2' D_2 \theta \end{aligned}$$

where D_2 is a difference matrix.

$P_2(\theta)$ is a **roughness penalty**.

Penalties

Eilers & Marx (1996) imposed **penalties** on **differences** between adjacent coefficients.

$$\begin{aligned} P_2(\theta) &= (\theta_1 - 2\theta_2 + \theta_3)^2 + \dots + (\theta_{p-2} - 2\theta_{p-1} + \theta_p)^2 \\ &= \theta' D_2' D_2 \theta \end{aligned}$$

where D_2 is a difference matrix.

$P_2(\theta)$ is a **roughness penalty**.

Estimation is via **penalised likelihood**

$$PL(\theta) = L(\theta) - \frac{1}{2}\lambda\theta' D_2' D_2 \theta$$

where λ is the **smoothing parameter** which balances **fit** and **smoothness**.

Penalties

Eilers & Marx (1996) imposed **penalties** on **differences** between adjacent coefficients.

$$\begin{aligned} P_2(\theta) &= (\theta_1 - 2\theta_2 + \theta_3)^2 + \dots + (\theta_{p-2} - 2\theta_{p-1} + \theta_p)^2 \\ &= \theta' D_2' D_2 \theta \end{aligned}$$

where D_2 is a difference matrix.

$P_2(\theta)$ is a **roughness penalty**.

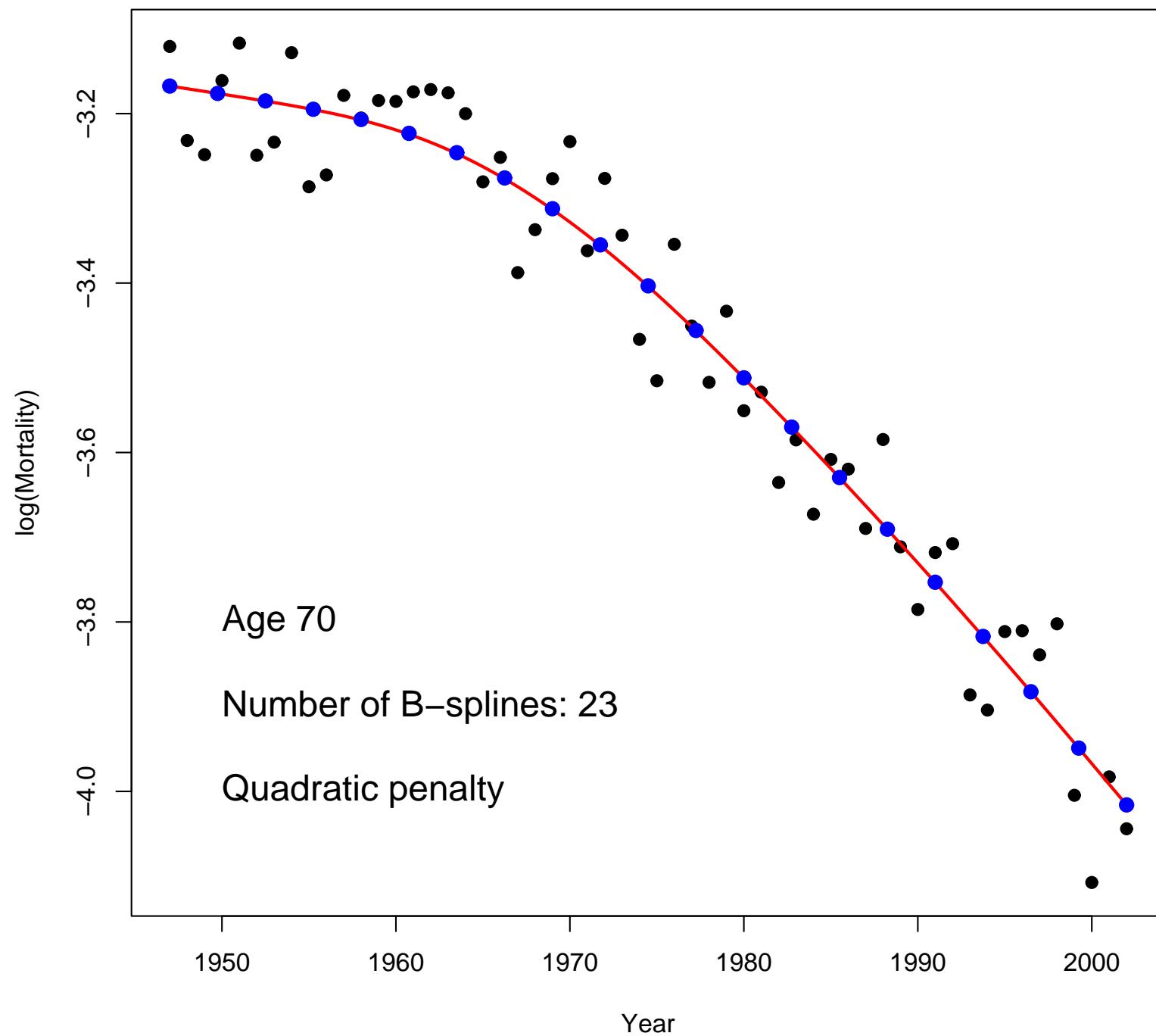
Estimation is via **penalised likelihood**

$$PL(\theta) = L(\theta) - \frac{1}{2}\lambda\theta' D_2' D_2 \theta$$

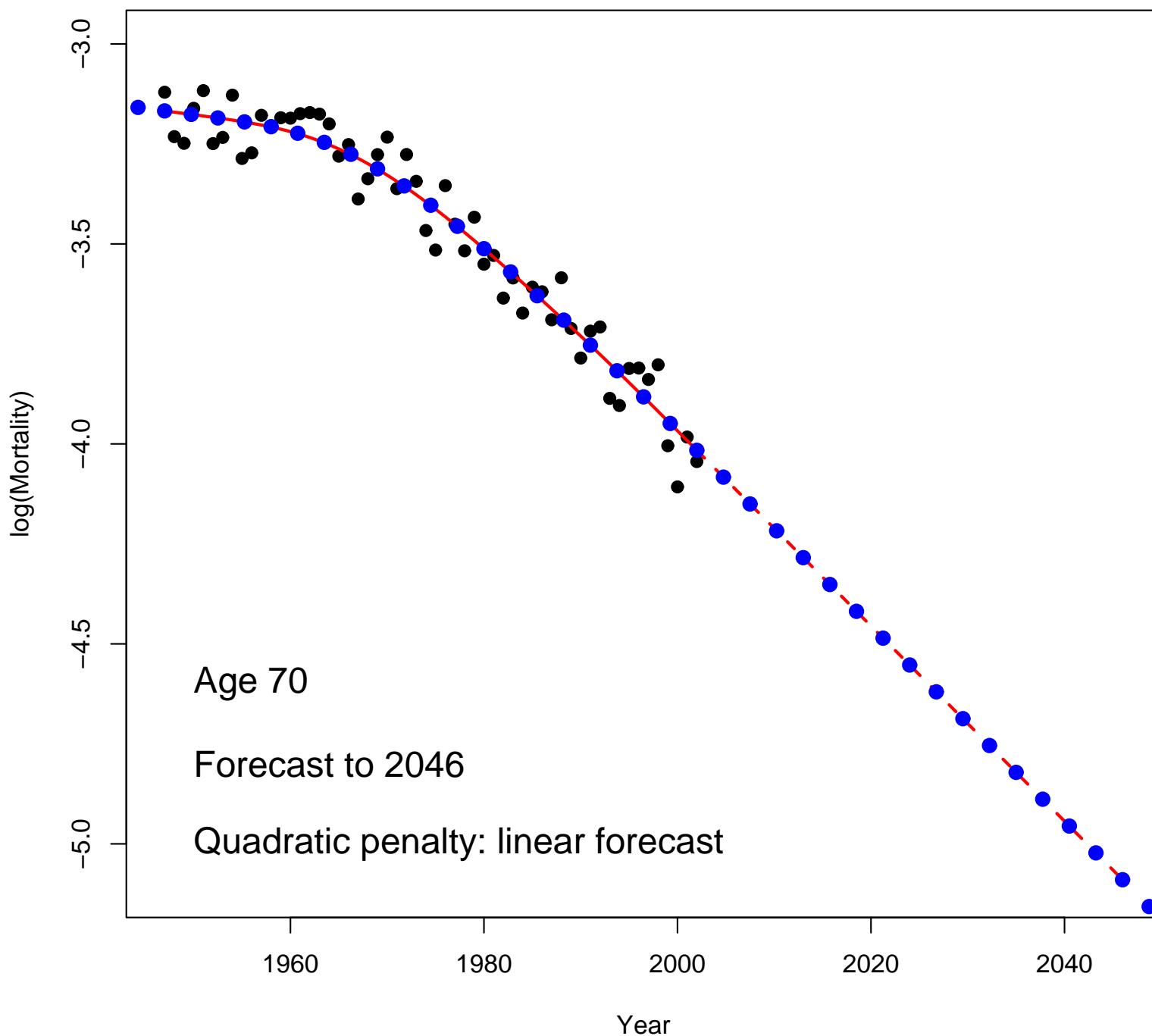
where λ is the **smoothing parameter** which balances **fit** and **smoothness**.

- Interpolation ($\lambda = 0$)
- Linear regression ($\lambda = \infty$)

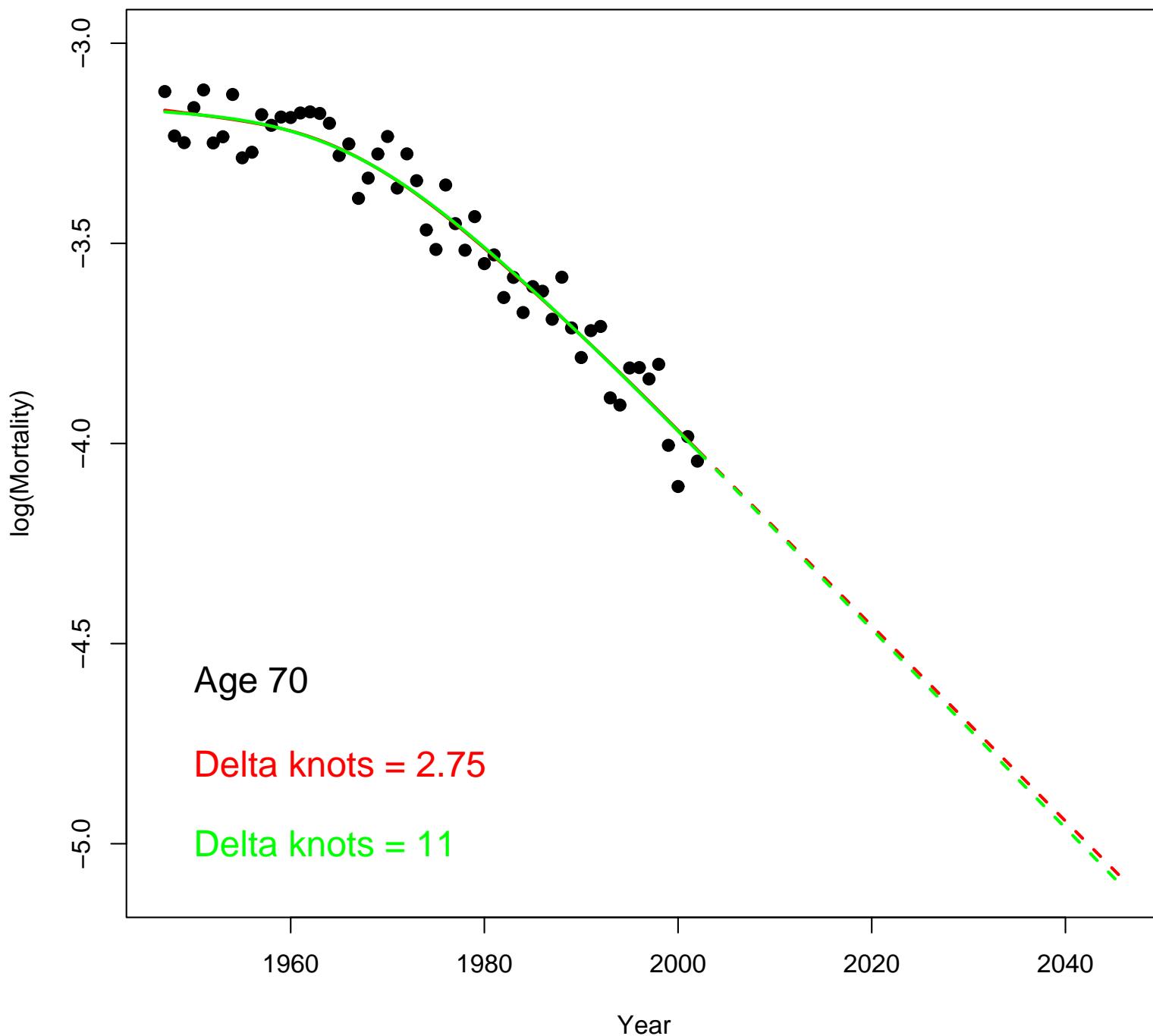
P-spline regression



Forecasting to 2046



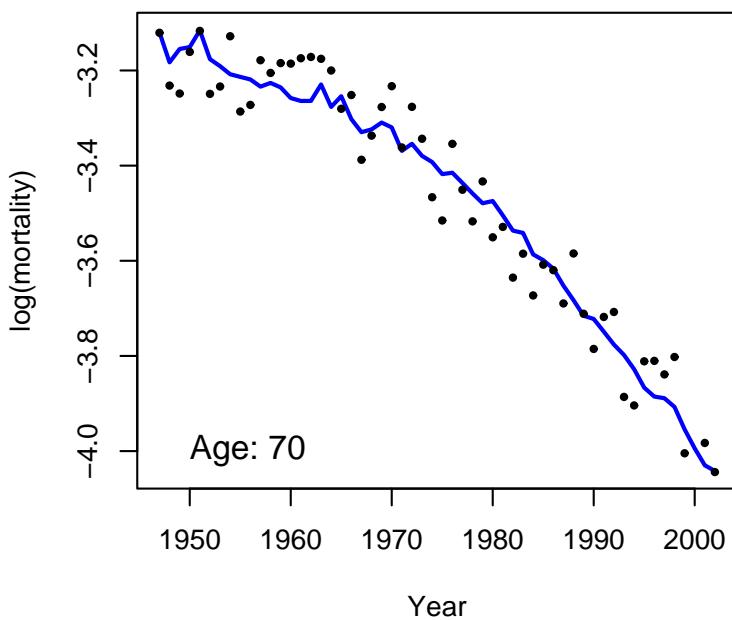
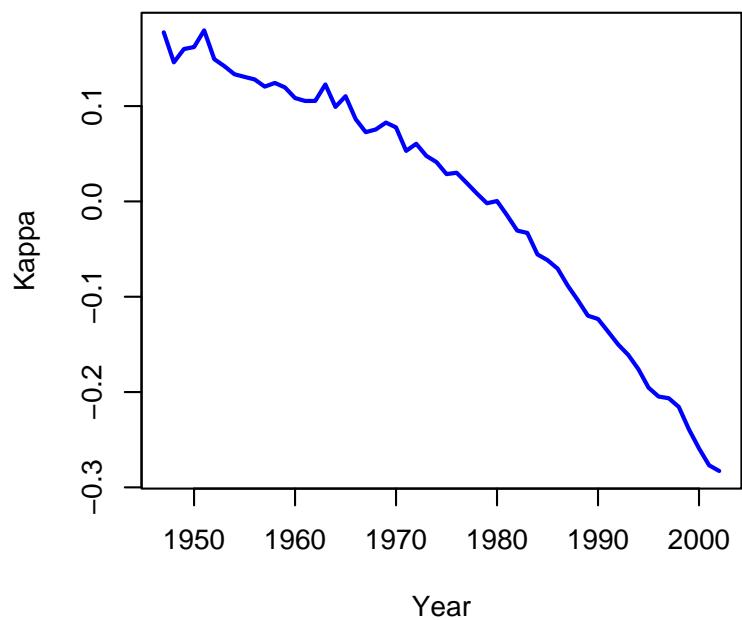
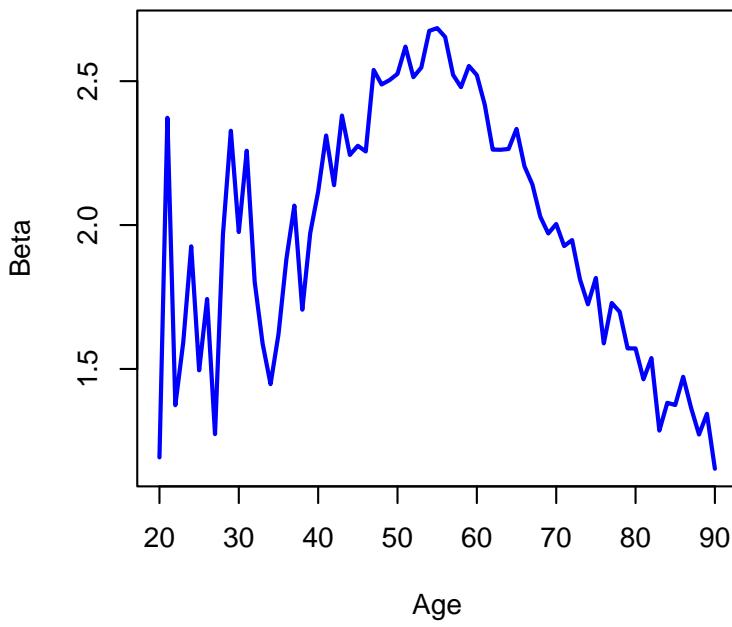
Forecasting to 2046

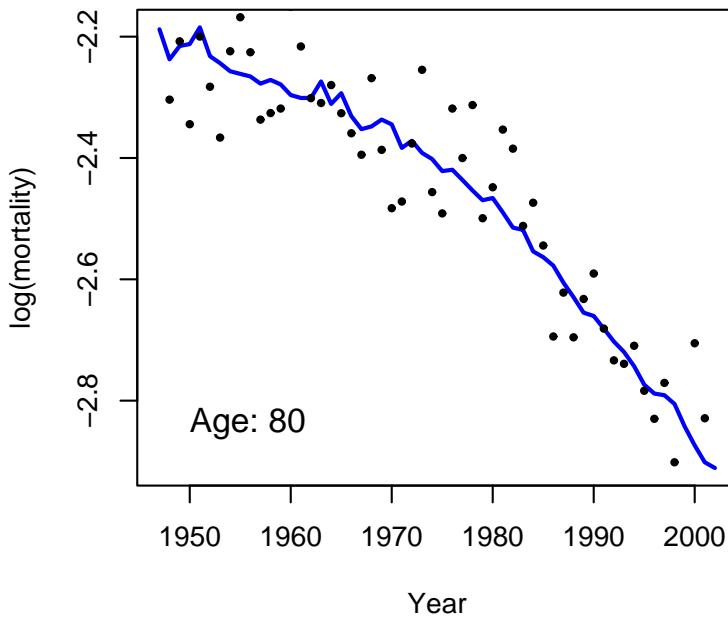
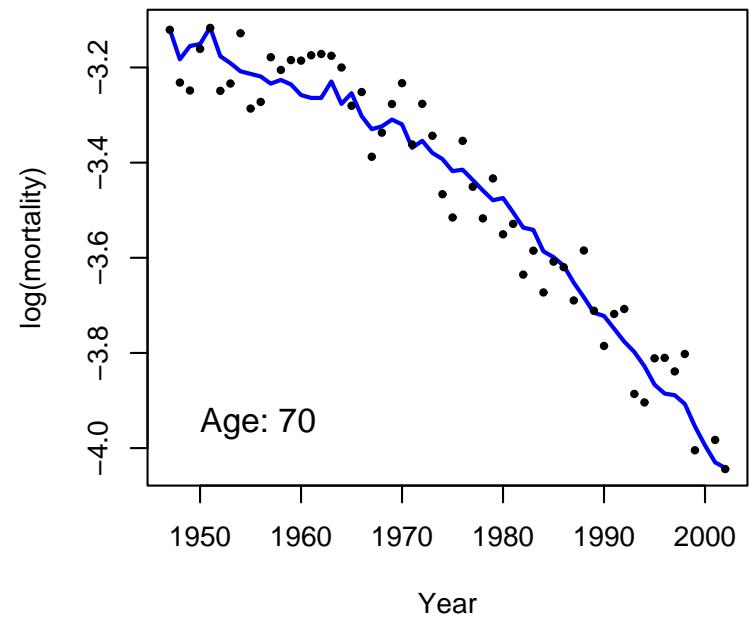
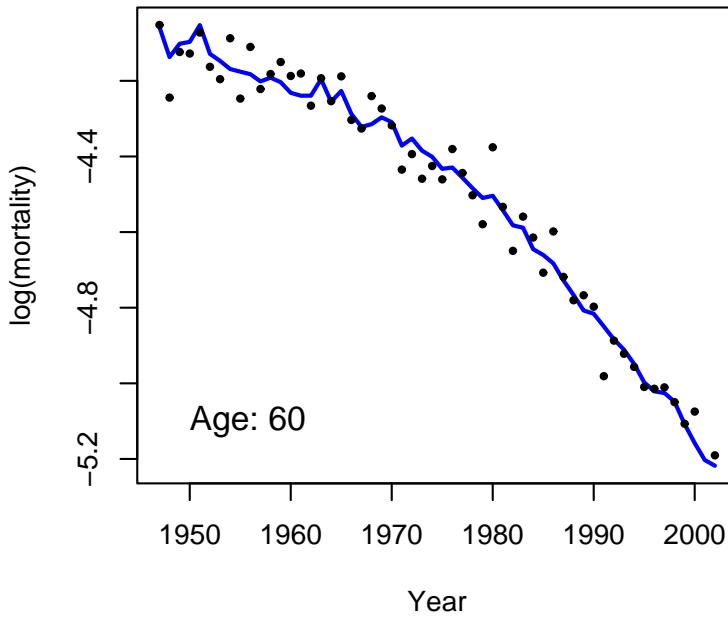
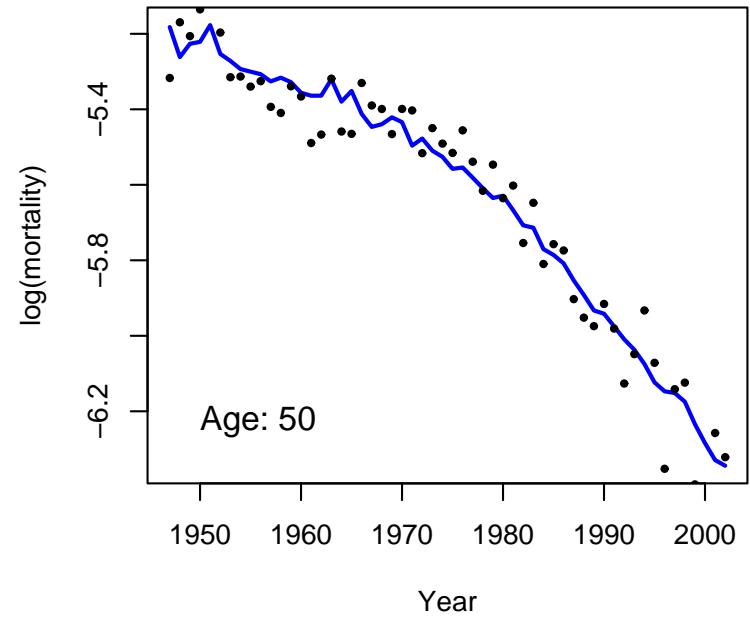


Lee-Carter model

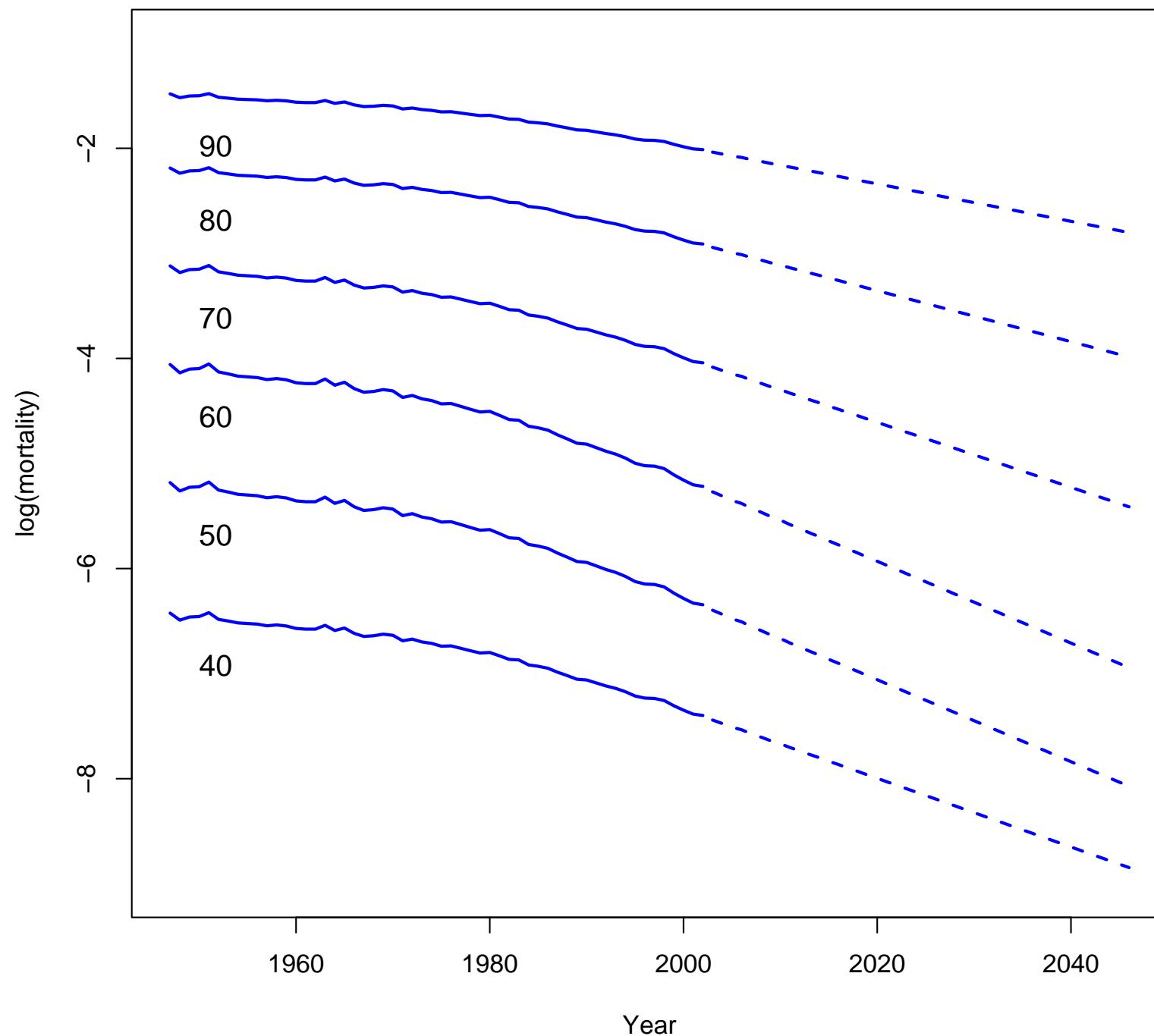
Lee & Carter (1992)

$$\log \mu_{ij} = \alpha_i + \beta_i \kappa_j, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$





Lee–Carter forecasts to 2046



Discrete Lee-Carter model

$$\log \mu_{ij} = \alpha_i + \beta_i \kappa_j, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$

or in table form

$$\log M = \alpha \mathbf{1}' + \beta \boldsymbol{\kappa}'$$

Discrete Lee-Carter model

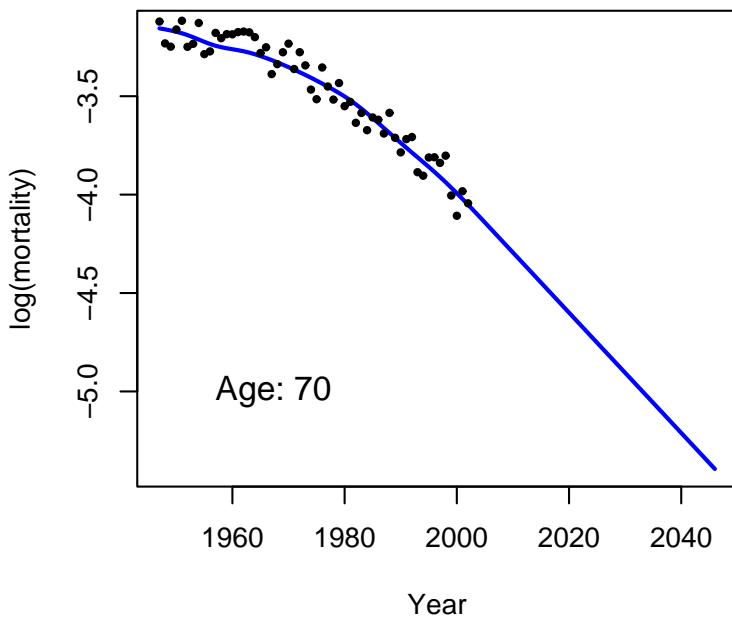
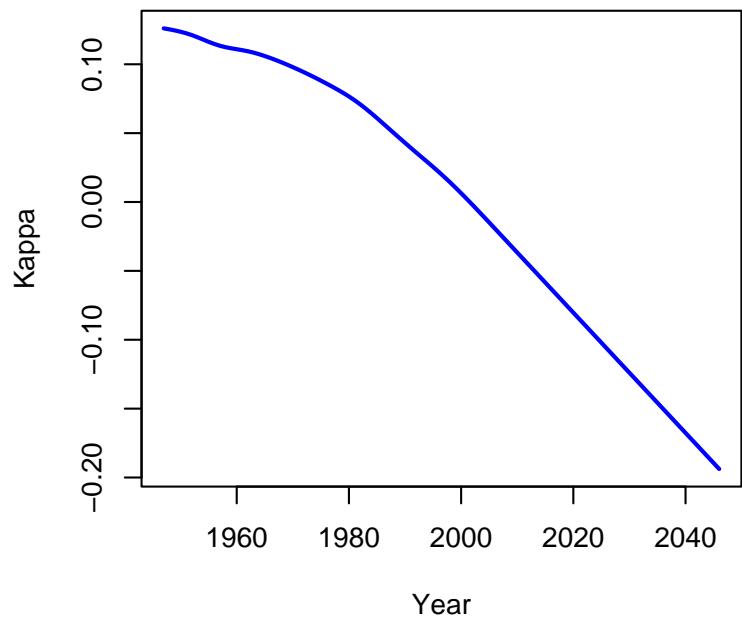
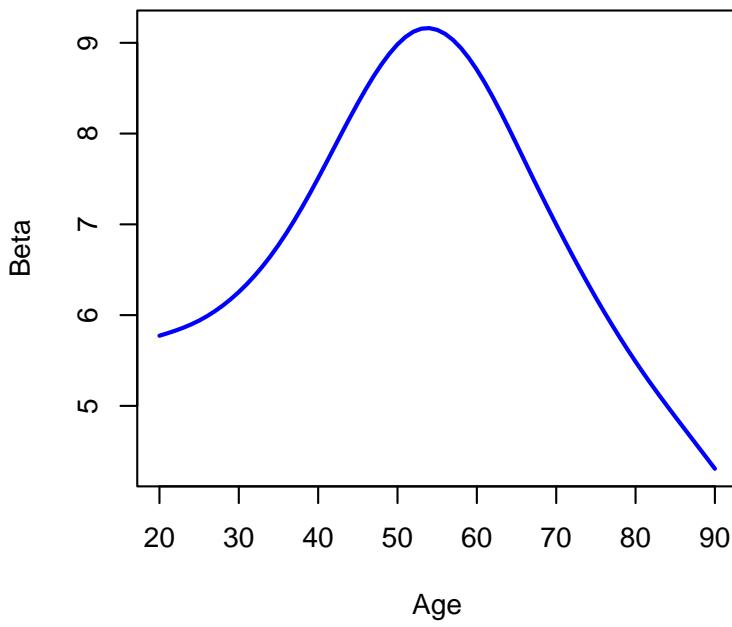
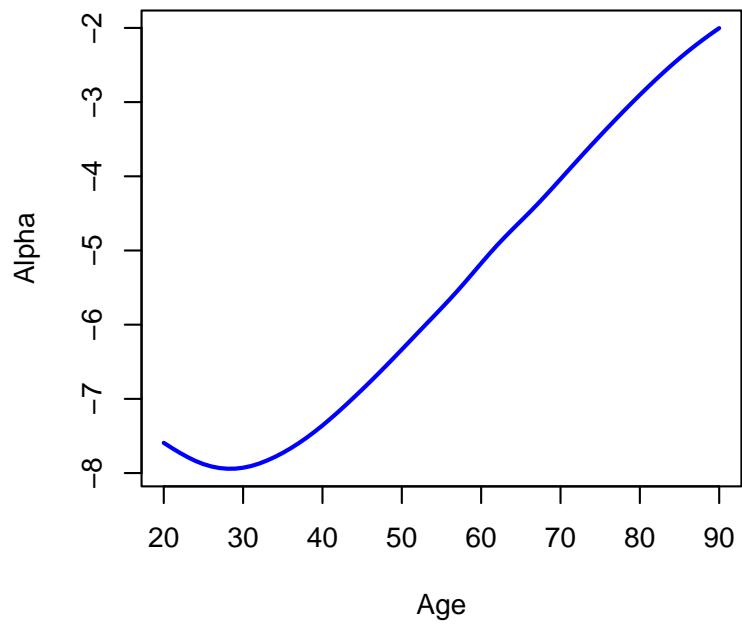
$$\log \mu_{ij} = \alpha_i + \beta_i \kappa_j, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$

or in table form

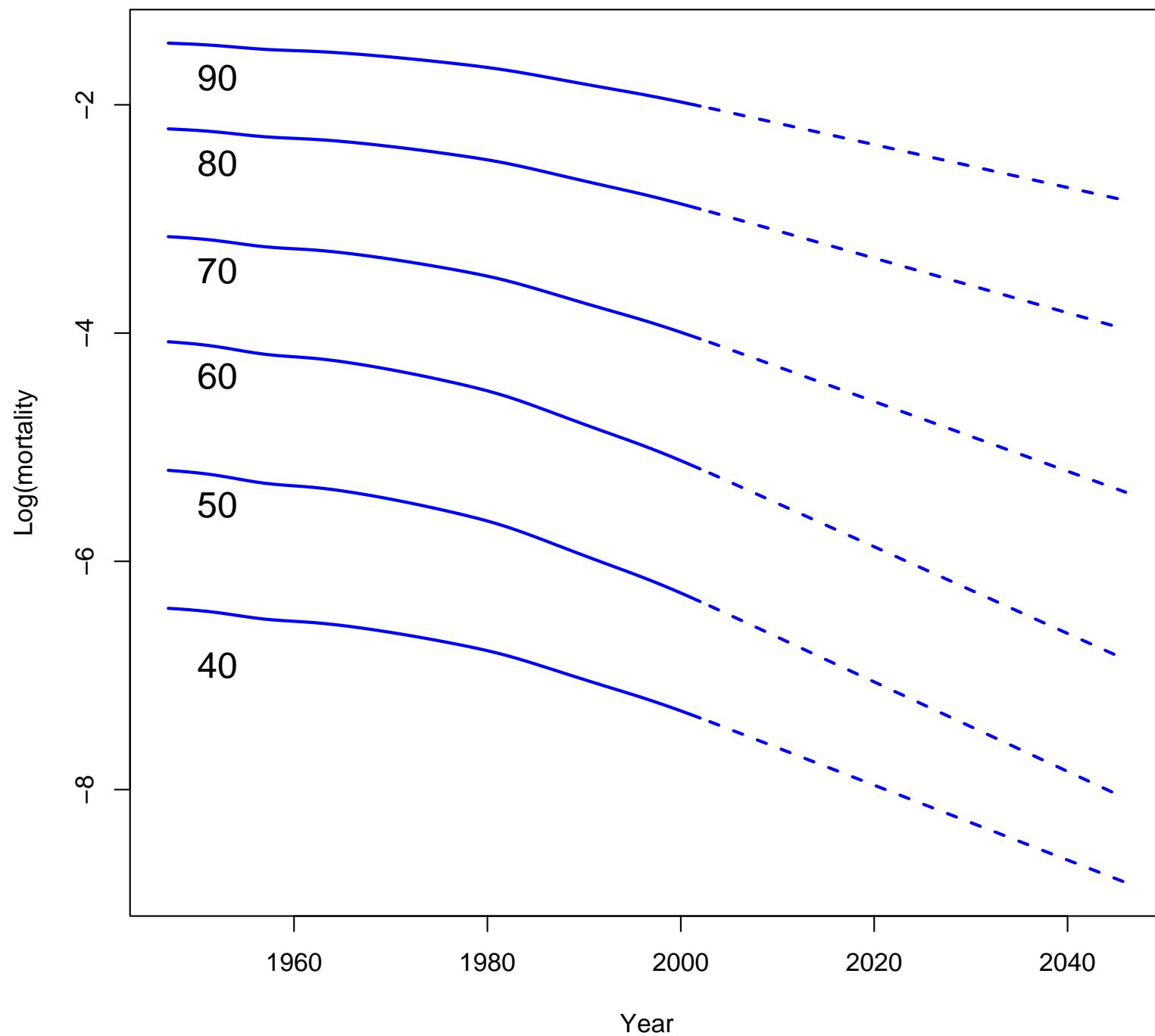
$$\log M = \boldsymbol{\alpha} \mathbf{1}' + \boldsymbol{\beta} \boldsymbol{\kappa}'$$

Smooth Lee-Carter

$$\boldsymbol{\alpha} \rightarrow \mathbf{B}_a \mathbf{a}, \quad \boldsymbol{\beta} \rightarrow \mathbf{B}_a \mathbf{b}, \quad \boldsymbol{\kappa} \rightarrow \mathbf{B}_y \mathbf{k}$$



Smooth Lee–Carter: ages 40 to 90



Age-Period-Cohort model

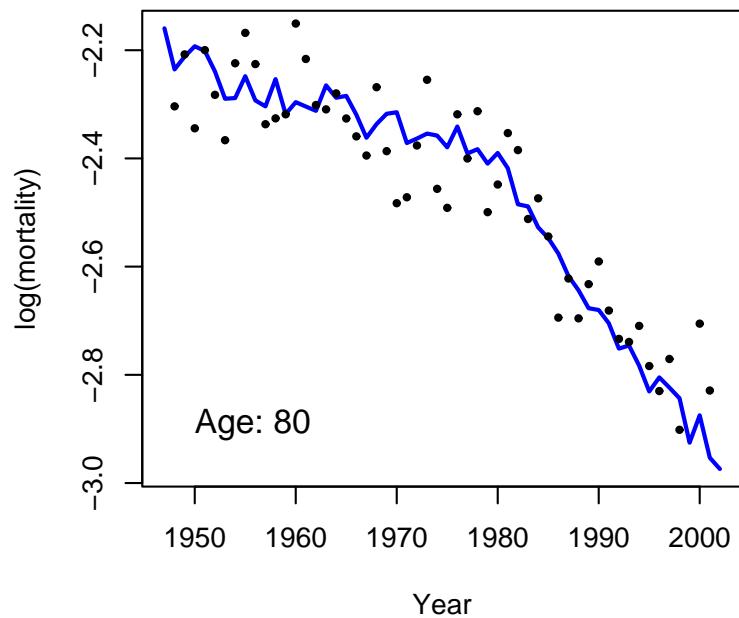
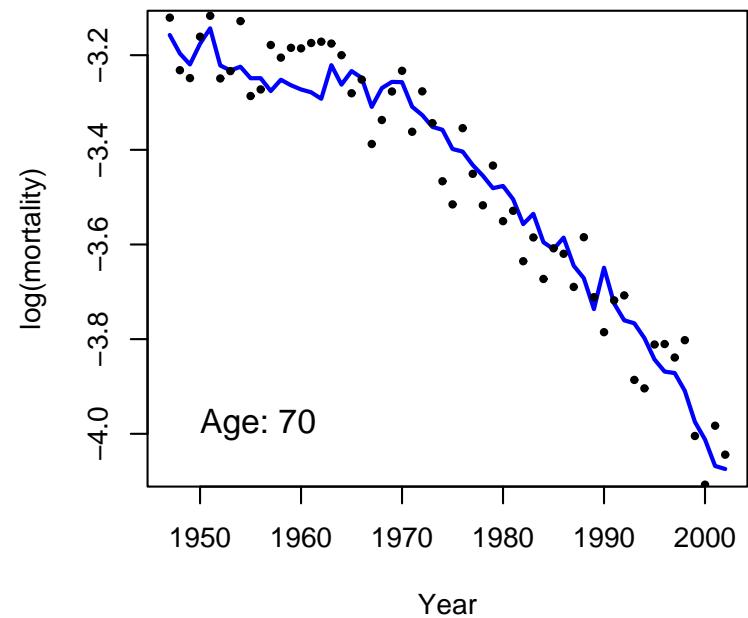
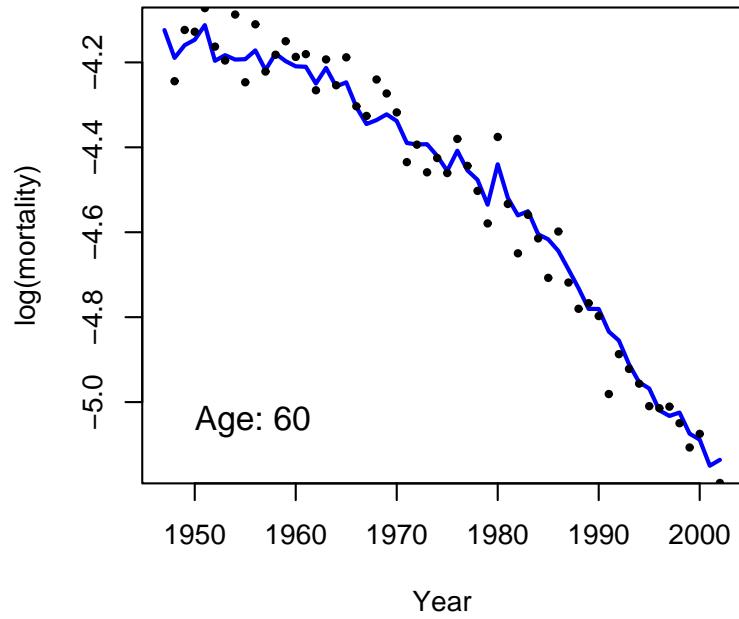
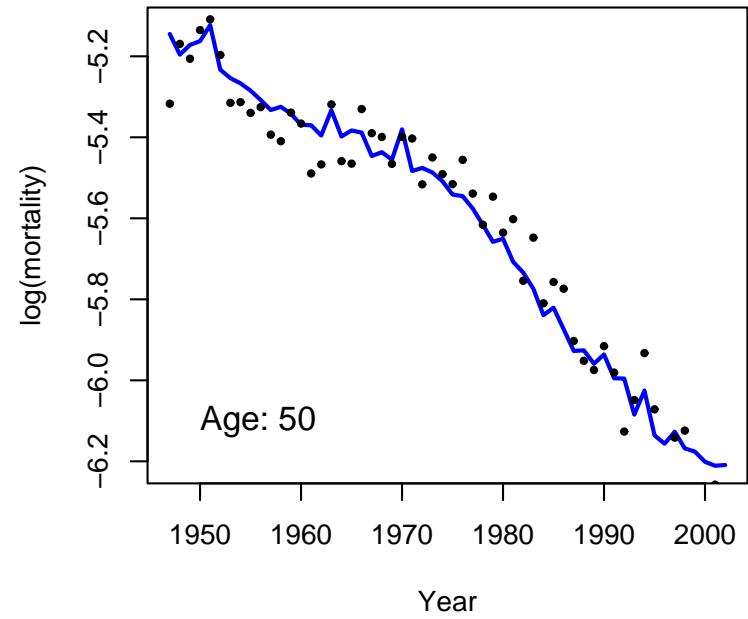
$$\log \mu_{ij} = \alpha_i + \beta_j + \gamma_{i-j}, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$

Age-Period-Cohort model

$$\log \mu_{ij} = \alpha_i + \beta_j + \gamma_{i-j}, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$

Parameter redundancy

- $2n_a + 2n_y - 1 = 253$ parameters
- $2n_a + 2n_y - 4 = 250$ free parameters



Discrete Age-Period-Cohort model

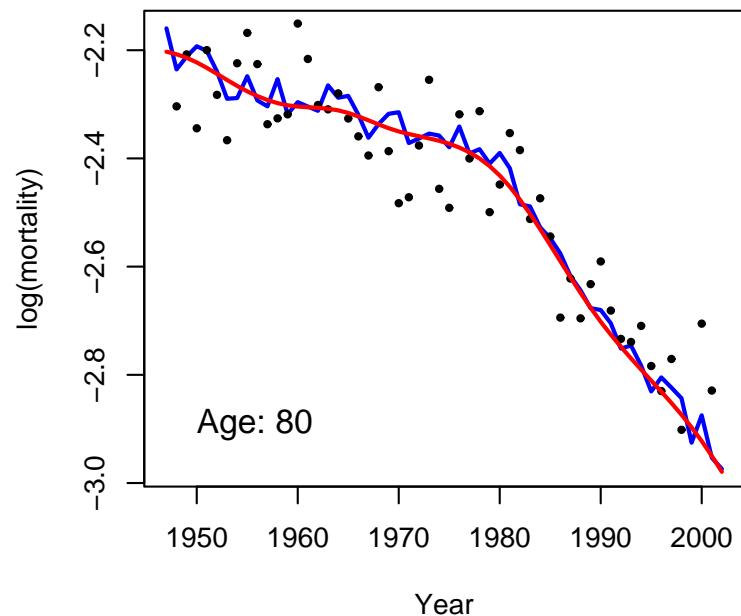
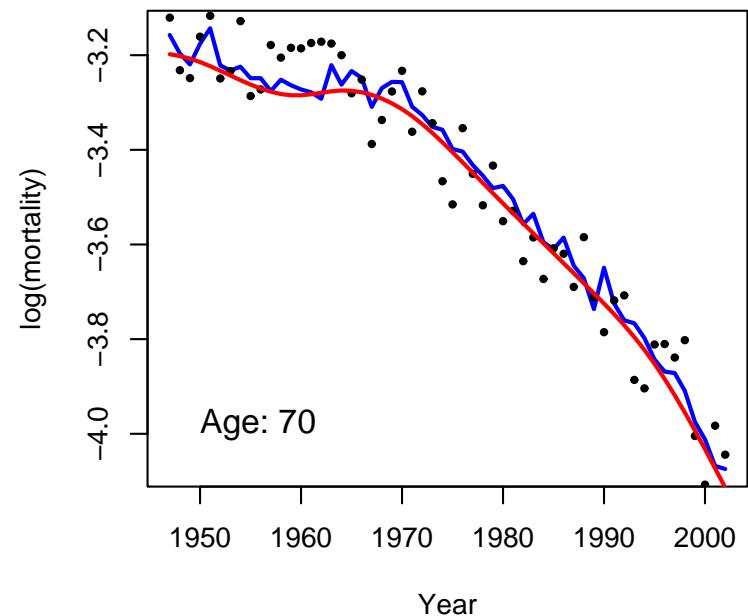
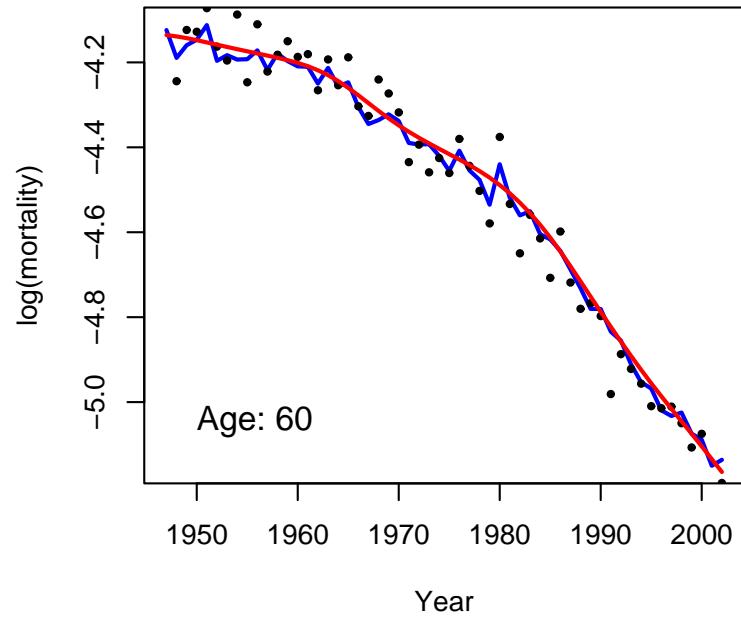
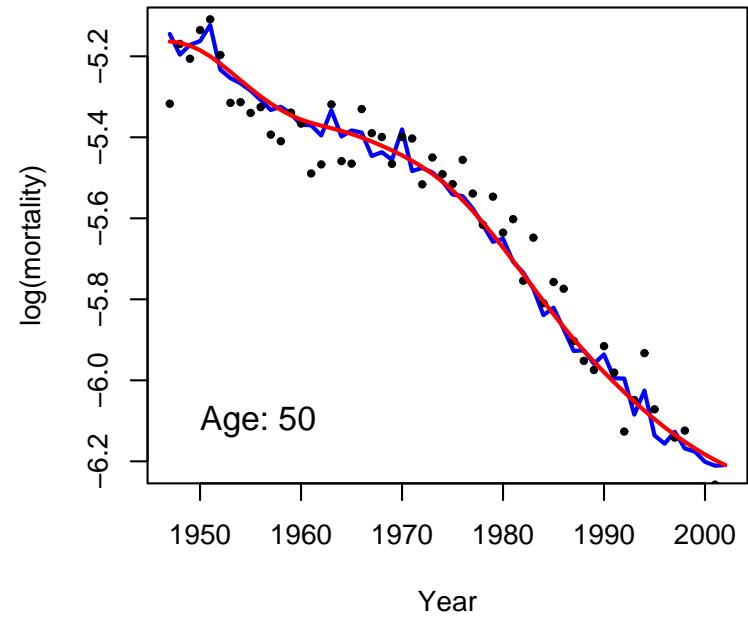
$$\log \mu_{ij} = \alpha_i + \beta_j + \gamma_{i-j}, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$

Discrete Age-Period-Cohort model

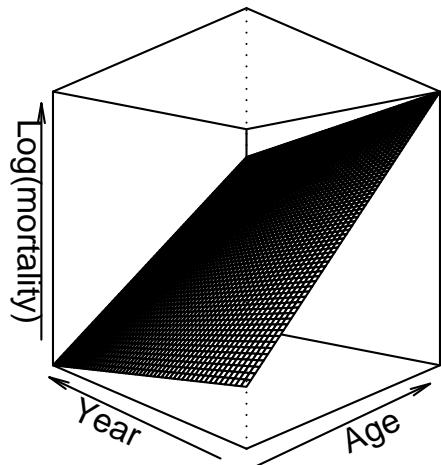
$$\log \mu_{ij} = \alpha_i + \beta_j + \gamma_{i-j}, \quad 20 \leq i \leq 90, \quad 1947 \leq j \leq 2002$$

Smooth Age-Period-Cohort model

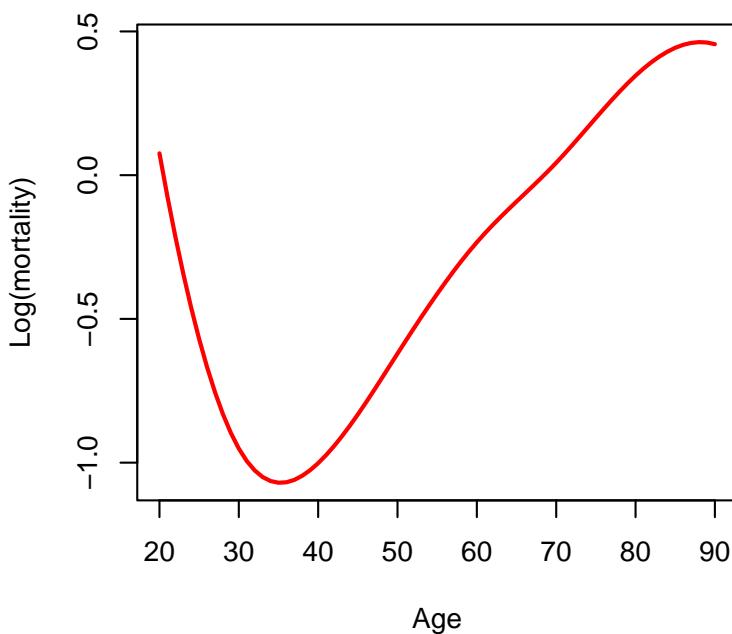
$$\boldsymbol{\alpha} \rightarrow \mathbf{B}_a \mathbf{a}, \quad \boldsymbol{\beta} \rightarrow \mathbf{B}_y \mathbf{b}, \quad \boldsymbol{\gamma} \rightarrow \mathbf{B}_c \mathbf{c}$$



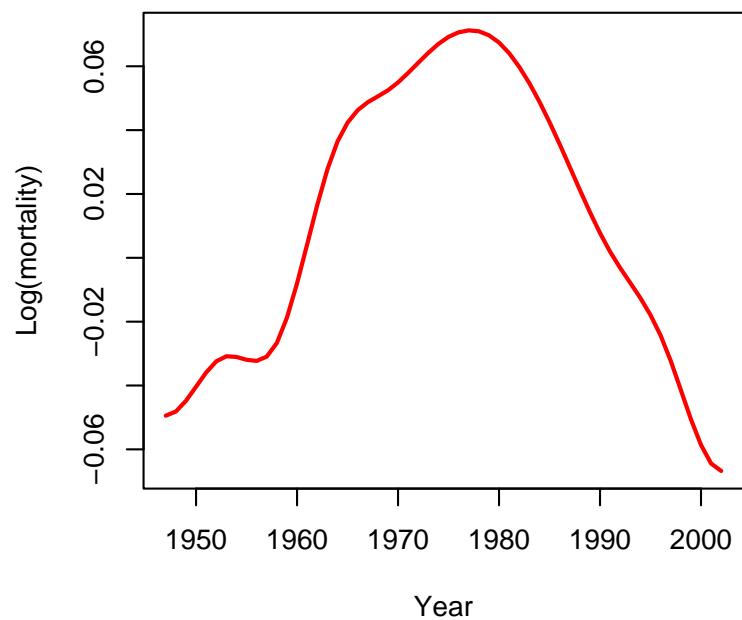
Planar component



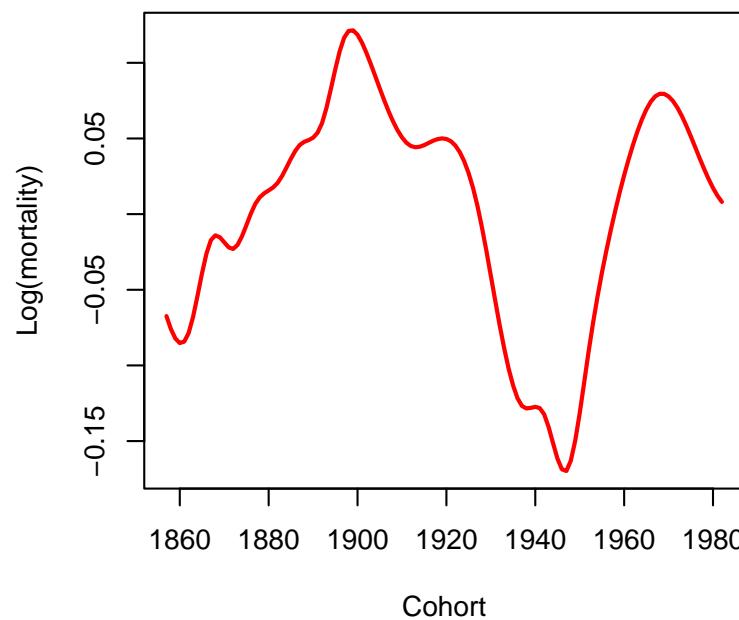
Age component



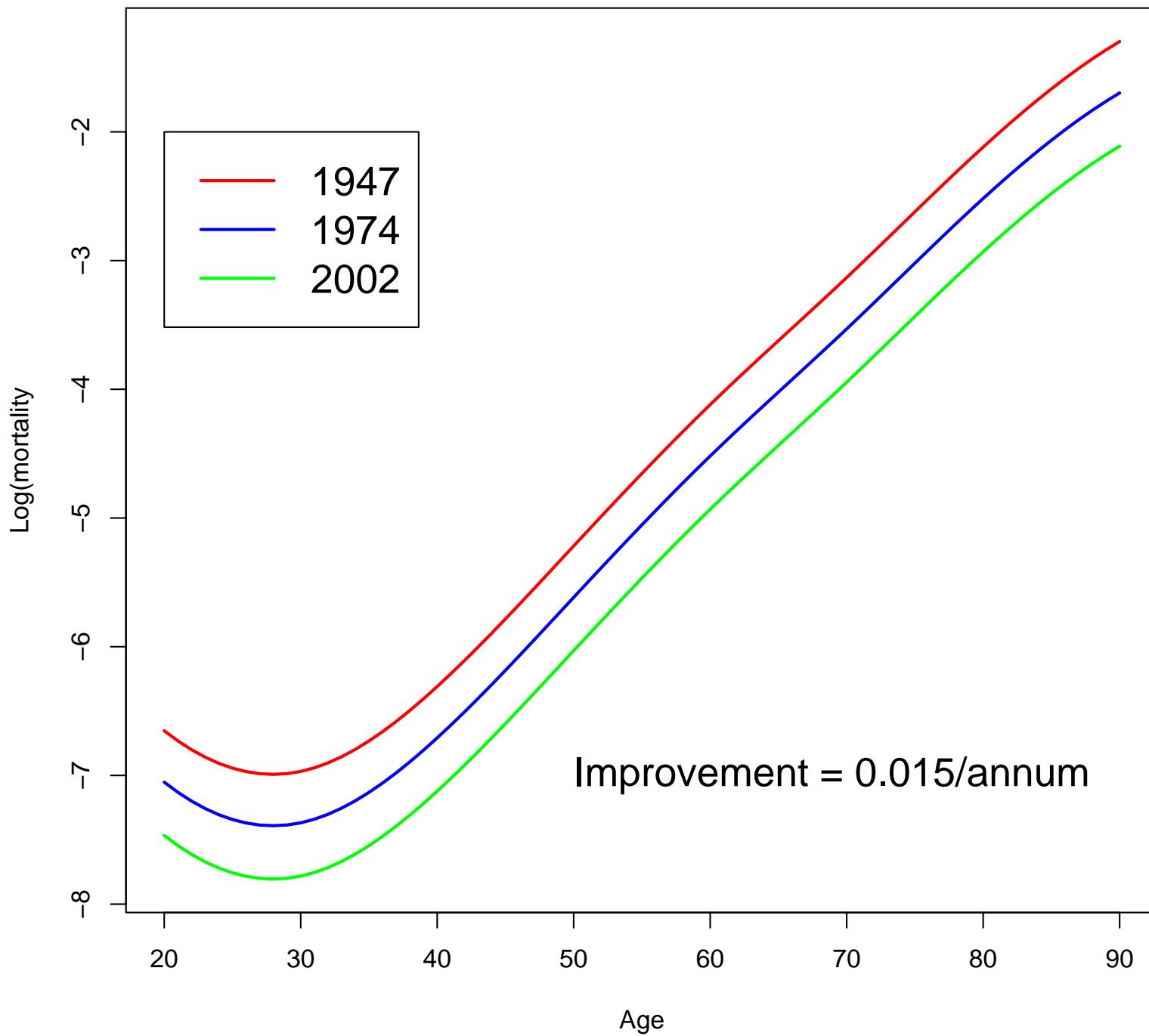
Year component



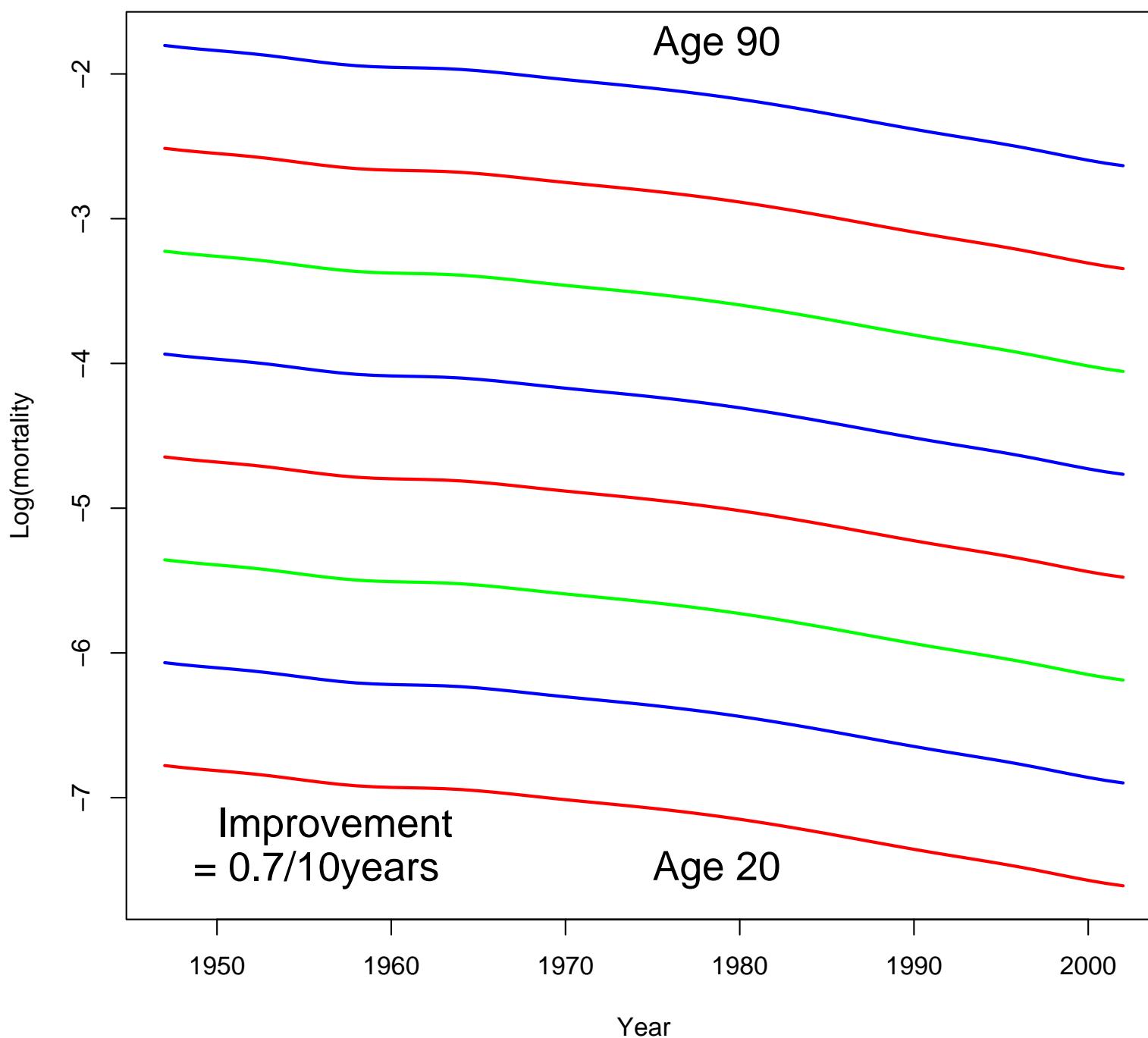
Cohort component



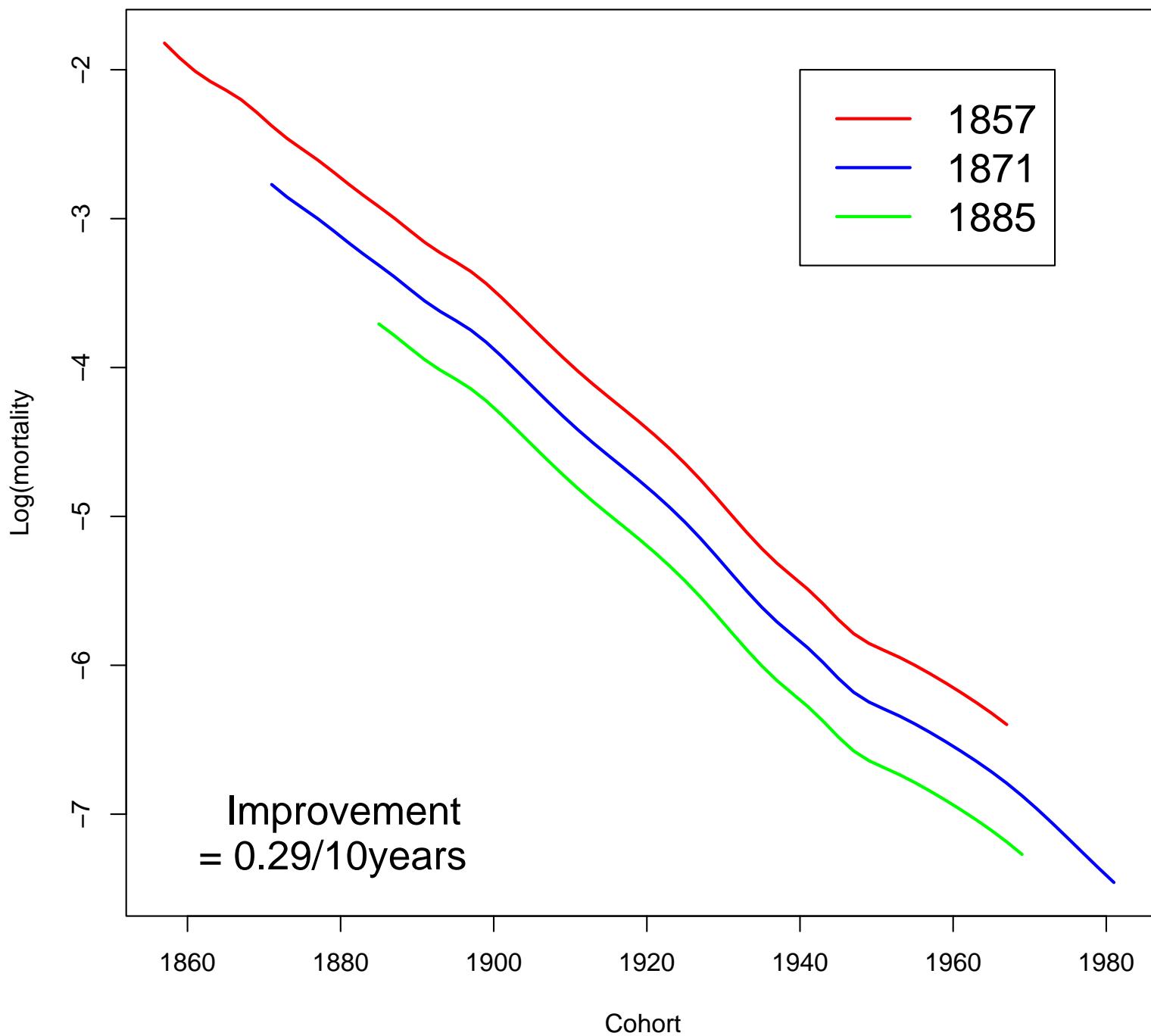
Components of Age



Components of Year



Components of Cohort



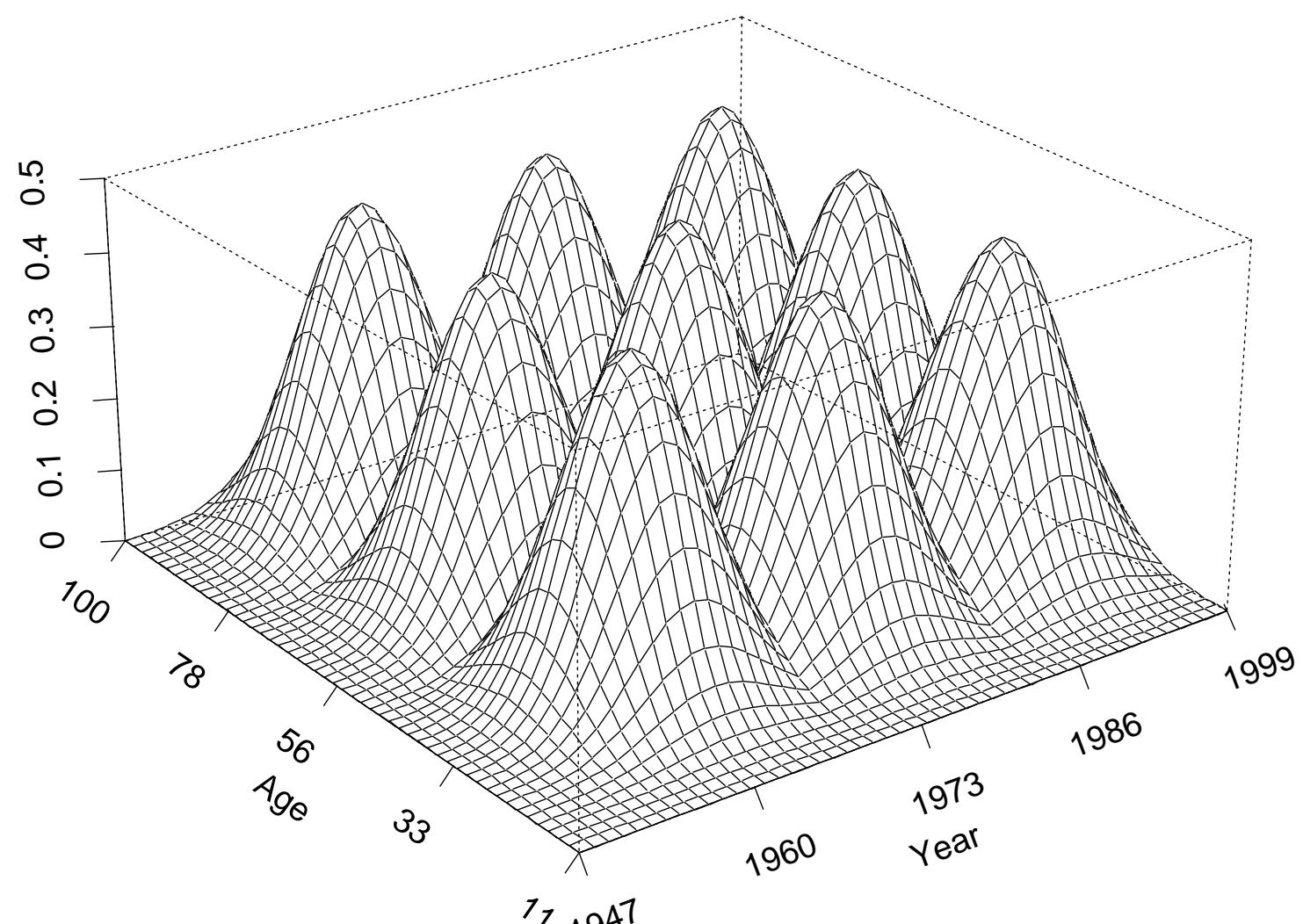
2-d modelling of mortality tables

- Let B_a , 71×13 , be a 1- d B-spline basis for modelling a **single age**.
- Let B_y , 56×10 , be a 1- d B-spline basis for modelling a **single year**.

2-d modelling of mortality tables

- Let B_a , 71×13 , be a 1- d B-spline basis for modelling a **single age**.
- Let B_y , 56×10 , be a 1- d B-spline basis for modelling a **single year**.

Can we combine the **marginal** bases B_a and B_y to make a 2-d basis?



2-d modelling of mortality tables

Regression matrix

The Kronecker product organises the multiplication of the marginal bases to give the regression matrix

$$B = B_y \otimes B_a, \quad 3976 \times 130.$$

2-d modelling of mortality tables

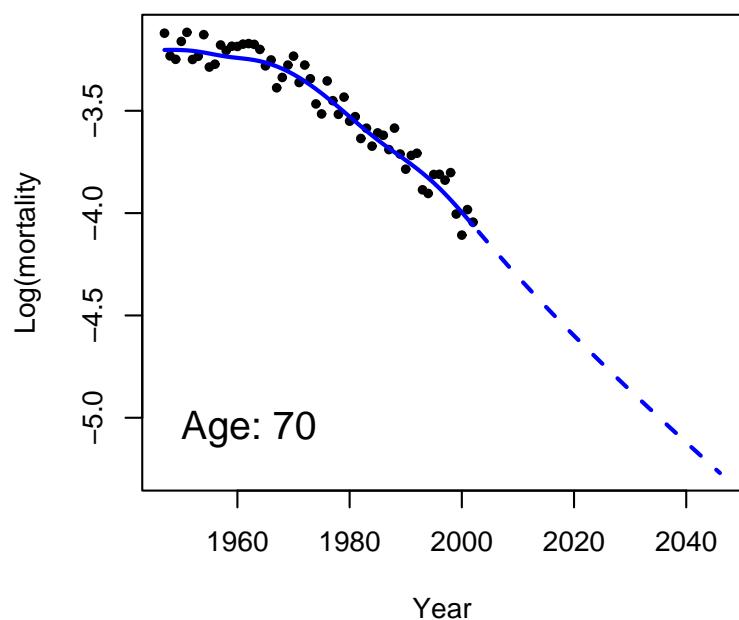
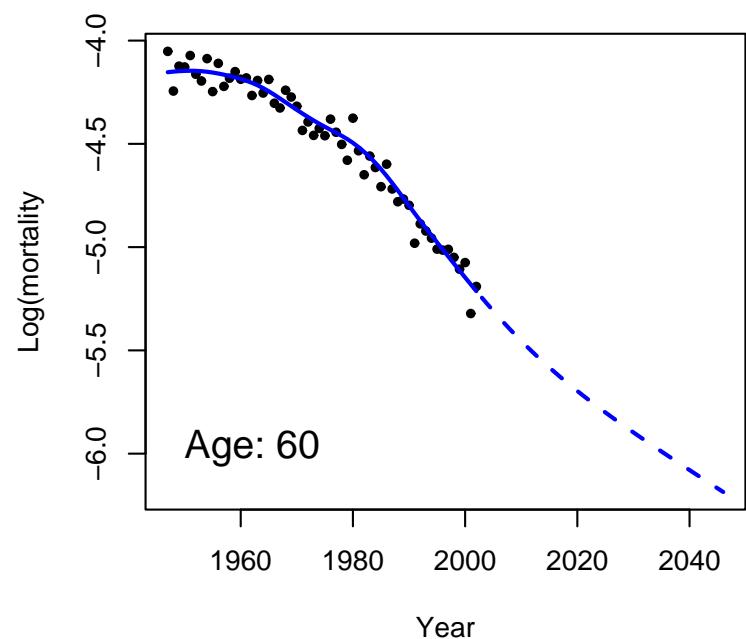
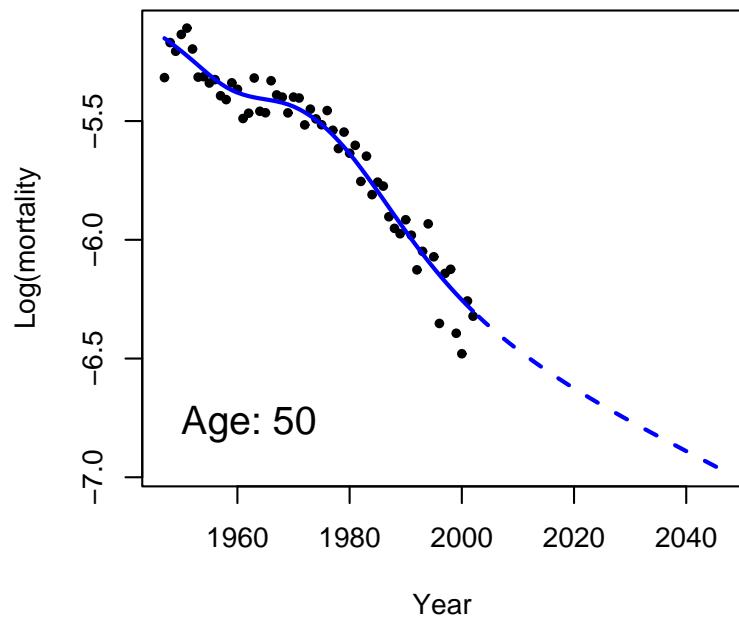
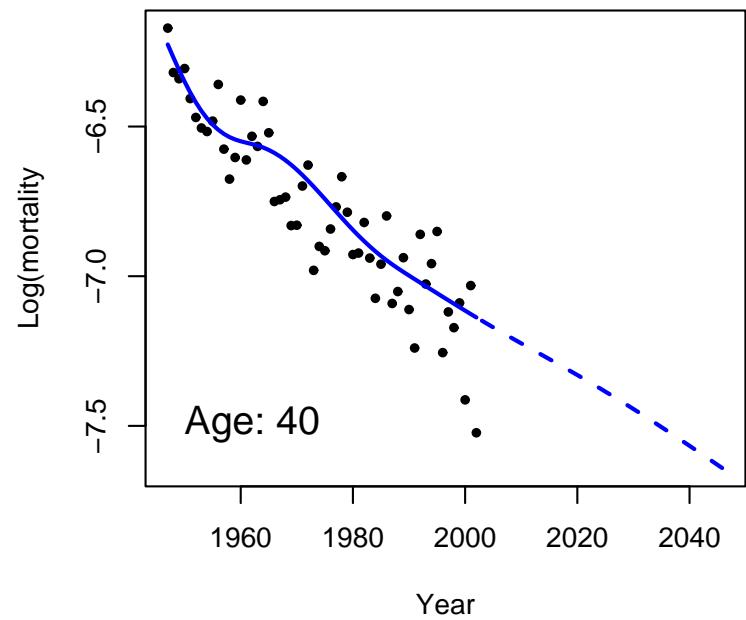
Regression matrix

The Kronecker product organises the multiplication of the marginal bases to give the regression matrix

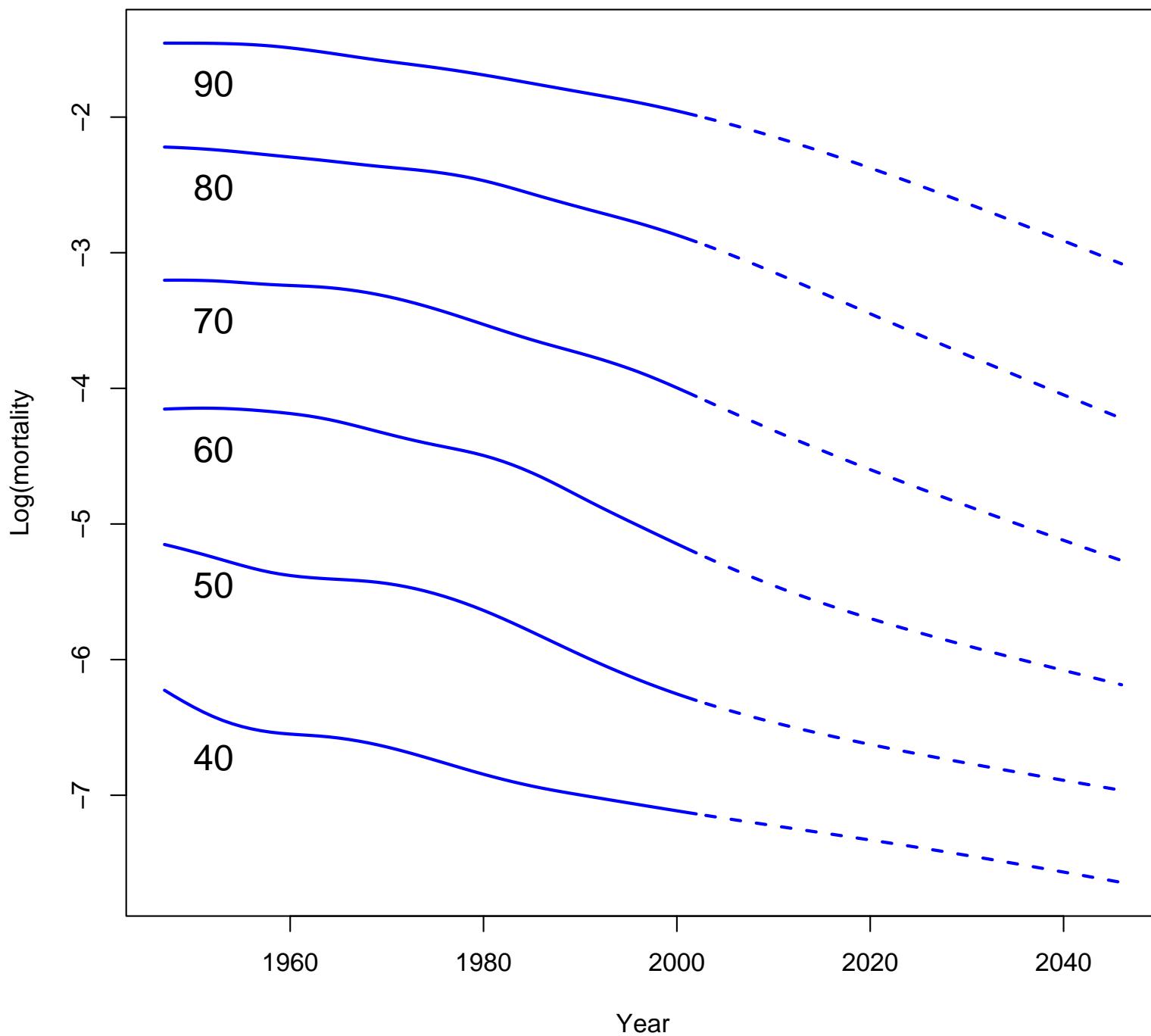
$$B = B_y \otimes B_a, \quad 3976 \times 130.$$

Penalties in 2-d

- Each regression coefficient is associated with the summit of one of the hills.
- Smoothness is ensured by penalizing the coefficients in rows and columns.



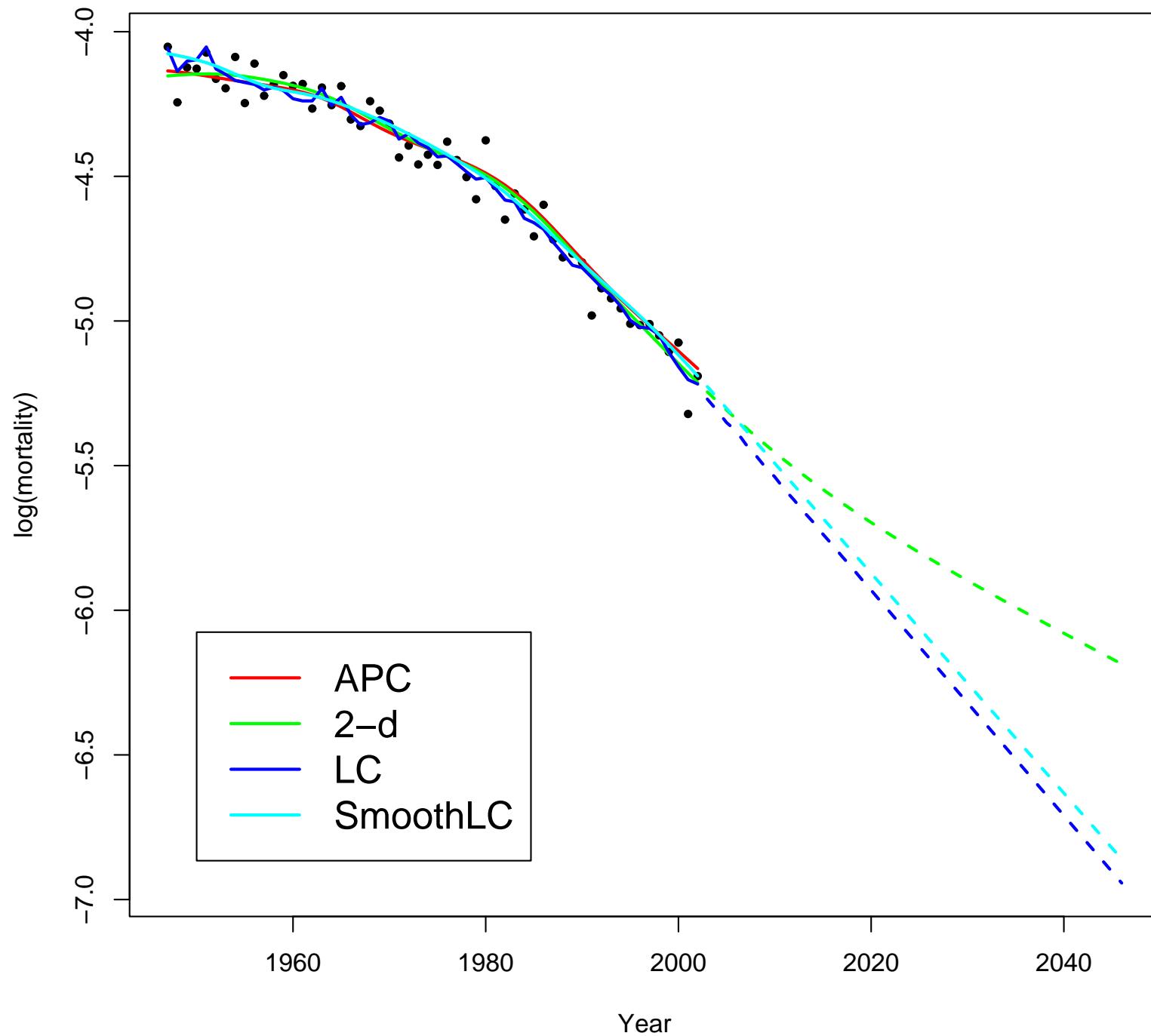
2-d mortality: ages 40 to 90



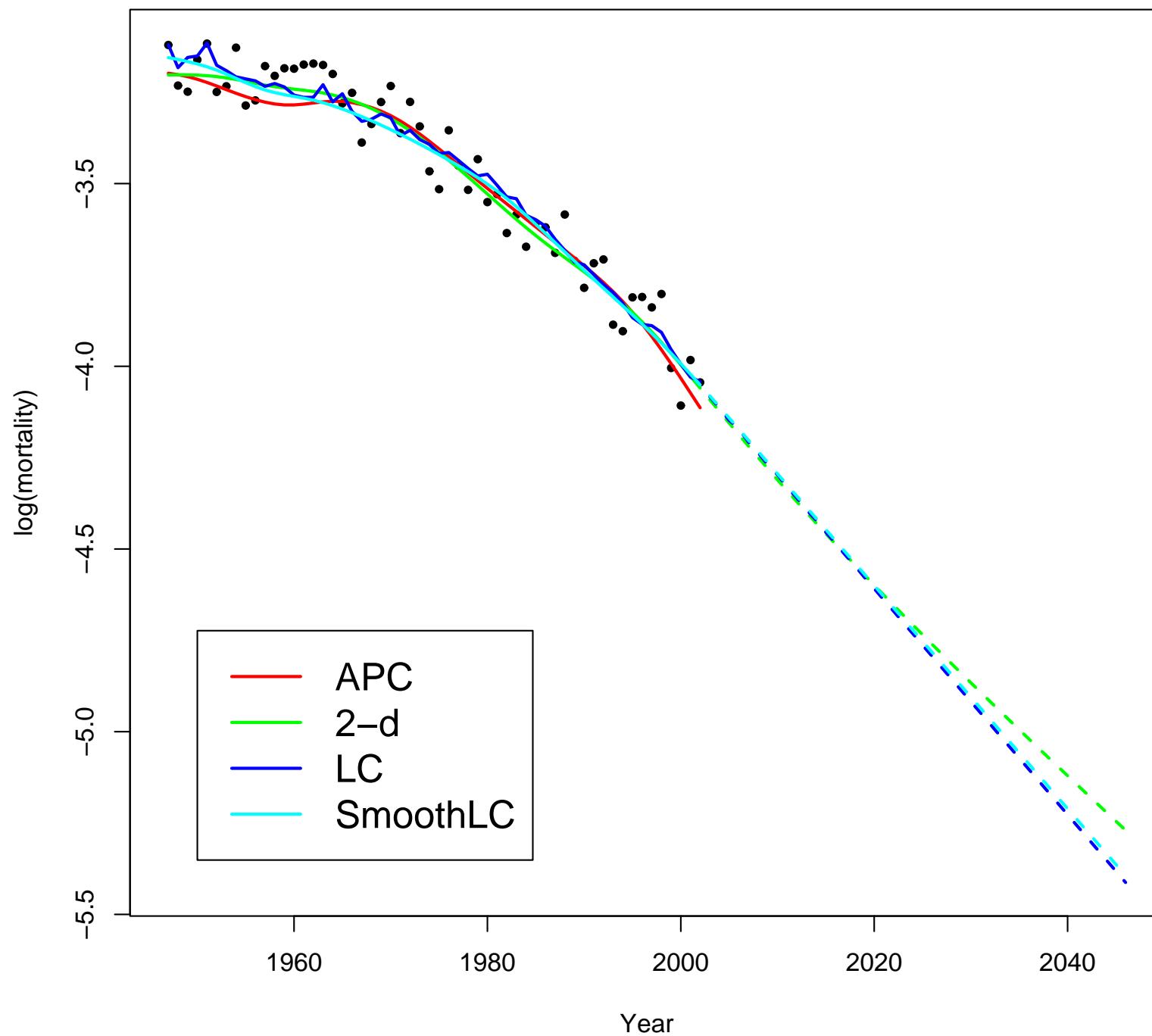
Summary of results

	DEV	TR	BIC	Rank
2-d	6832	63	7357	1
APC smooth	7852	38	8167	2
LC smooth	8568	30	8815	3
APC	7002	248	9057	4
LC	8004	196	9629	5

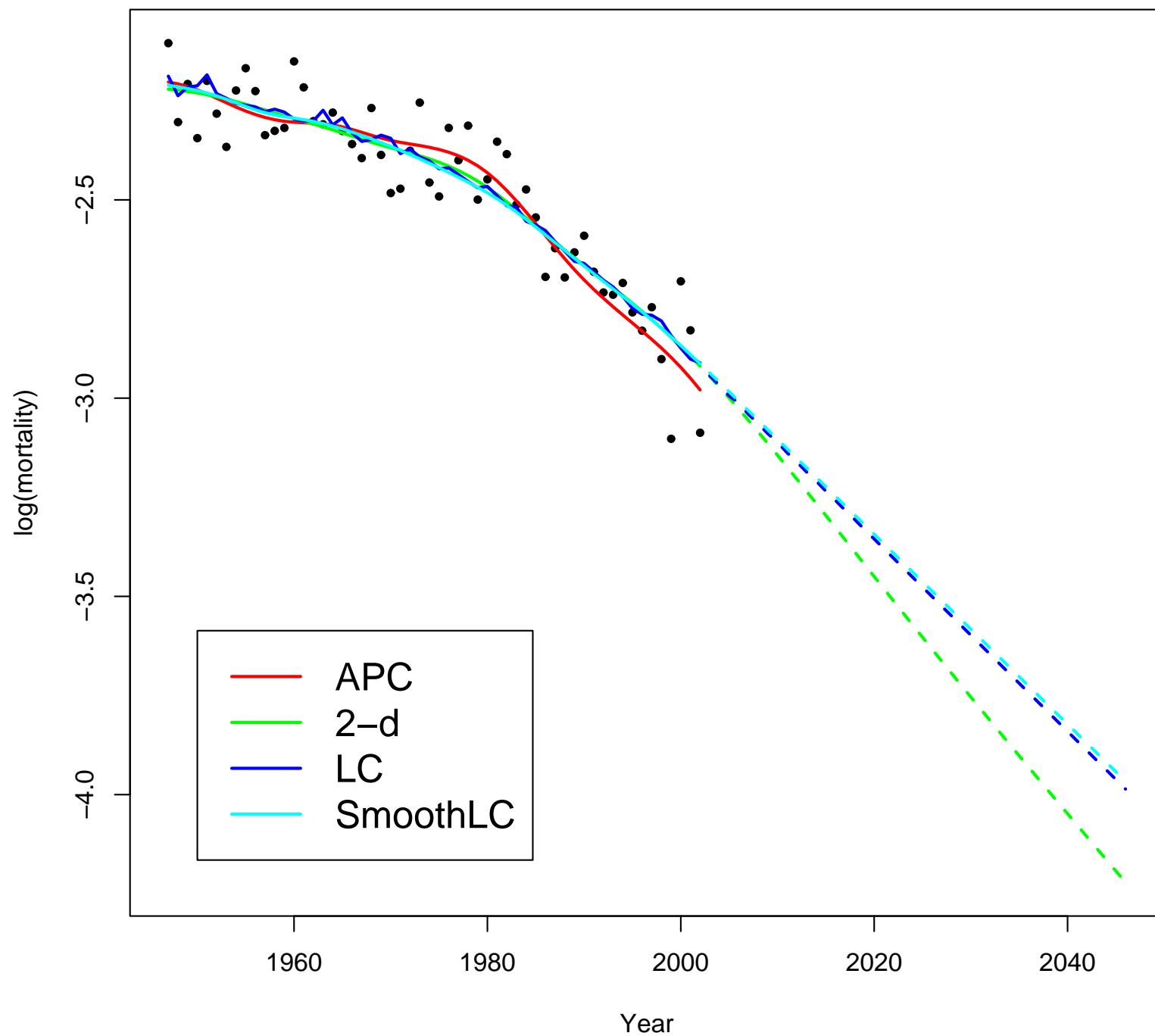
Summary for age 60



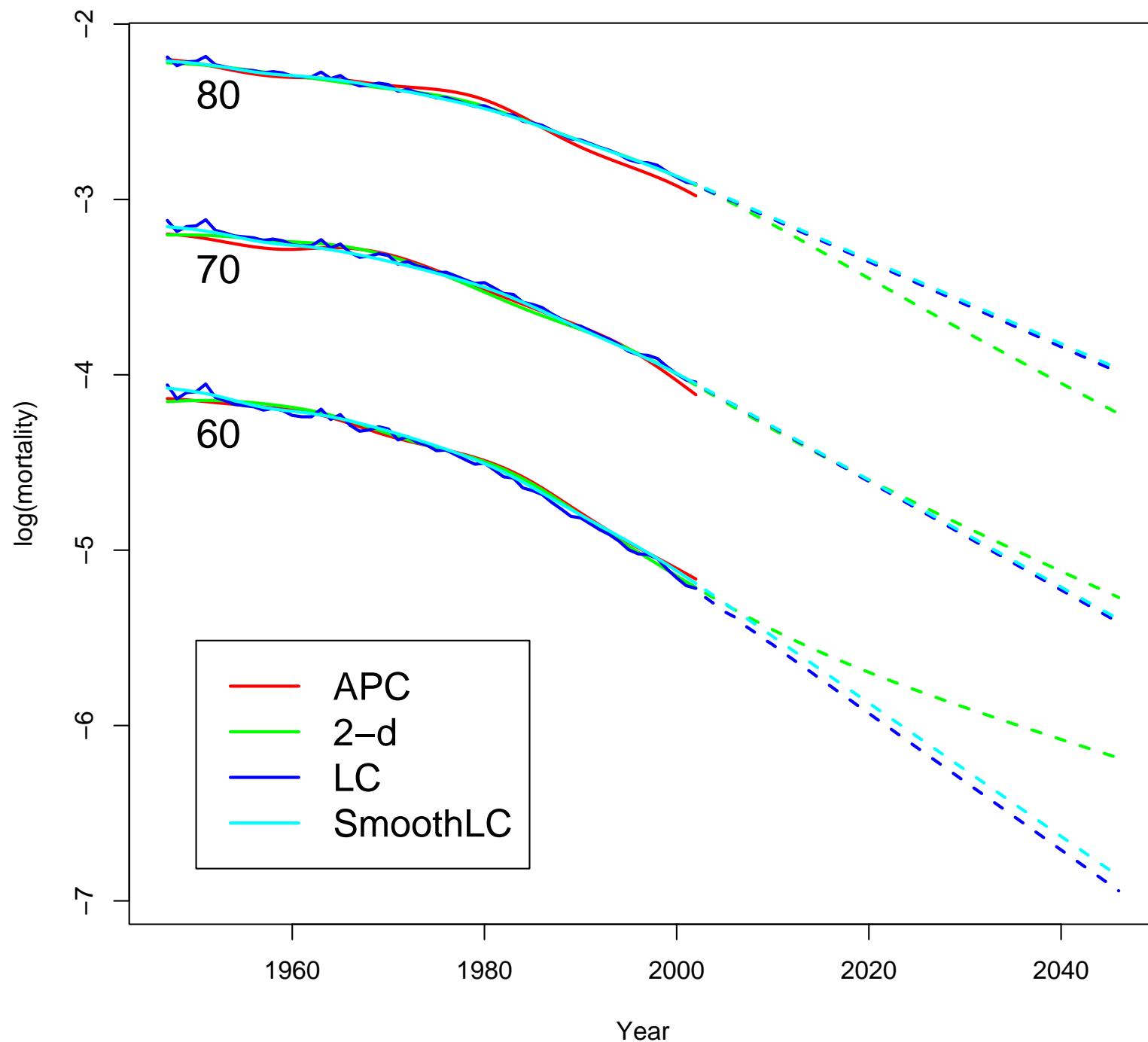
Summary for age 70



Summary for age 80



Summary for ages 60, 70, 80



Conclusions

Forecasting a mortality table depends on

Conclusions

Forecasting a mortality table depends on

- Model choice

Conclusions

Forecasting a mortality table depends on

- Model choice
- Forecasting method

Conclusions

Forecasting a mortality table depends on

- Model choice
- Forecasting method
- Parameter uncertainty

Conclusions

Forecasting a mortality table depends on

- Model choice
- Forecasting method
- Parameter uncertainty
- Stochastic uncertainty

References

Lee-Carter models

Lee & Carter (1992) J American Statistical Association, 87, 659-675.

Brouhns, Denuit & Vermunt (2002) Insurance: Mathematics & Economics, 31, 373-393.

Age-Period-Cohort models

Clayton & Schlifflers (1987) Statistics in Medicine, 6, 449-467.

Clayton & Schlifflers (1987) Statistics in Medicine, 6, 469-481.

Penalized spline models

Eilers & Marx (1996) Statistical Science, 11, 758-783.

Currie, Durban & Eilers (2004) Statistical Modelling, 4, 279-298.

Currie, Durban & Eilers (2006) Journal of the Royal Statistical Society, Series B, 68, 259-280.