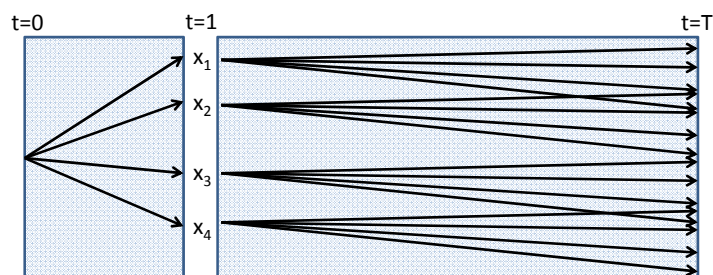


Difference between LSMC and Replicating Portfolios

Based on joint work with: Eric Beutner and Janina Schweizer at Maastricht University

Risk Calculations under Solvency II

- Price at t is calculated as conditional expectation under Q -measure for a specific scenario x at t
 - A scenario is a specific value for the relevant risk-drivers
- Mathematical notation: $\text{price}(t,x) = E^Q[f(S_T) \mid S_t=x]$
- How to compute this value?
 - “Brute force”: simulation-in-simulation
 - Alternative : fit a function at $t=1$ or $t=T$



Outline

- Approximation of Functions
- Approximation in Higher Dimensions
- Replicating Portfolio vs Function Fitting

Approximation of Functions

Approximation - Distance

- Consider a random variable S_T with a probability density function $p(S_T)$.
 - The variable S is a risk-driver, e.g. stock-price or interest rate.
- Consider a (payoff) function $f(S_T)$
 - For example: $f(S_T) = \max\{S_T - K, 0\}$ or $f(S_T) = \ln S_T$
- Consider another function $g(S_T)$.
- What is the “distance” between f and g ?
 - Distance = 0 $\Leftrightarrow f \equiv g$
 - Distance >0 for any $f \neq g$
 - Symmetry: $d(f,g) = d(g,f)$
 - Triangle inequality: $d(f,g) \leq d(f,h) + d(h,g)$ for all f,g,h

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Approximation - Distance

- Use “root mean square error” as distance:

$$d(f, g) = \left(\int (f(S) - g(S))^2 p(S) dS \right)^{\frac{1}{2}}$$

$$= E \left[(f(S) - g(S))^2 \right]^{\frac{1}{2}}$$
- Satisfies all properties
 - Only for $f \equiv g$ for all S do we get $d(f,g)=0$, otherwise $d(f,g)>0$
 - Makes intuitive sense: give more weight to errors with high probability
- This choice is not unique. Other distance functions are also possible.
 - For example: use different probability $q(S)$ or error-power.
 - “Norm equivalence”: convergence for one distance-function implies convergence in other norms as well.

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Approximation - Polynomials

- Approximate complicated payoff function $f(S)$ with “simple” functions.
 - Easy to compute market-price for the simple functions
- Example: choose polynomials S^k
- Approximate $f(S)$ with $\sum a_k (S_T)^k$ for $k=0\dots K$
 - Make smart choice for coefficients a_k
- Best choice: $\min d(f, \sum a_k S^k) = E[(f - \sum a_k S^k)^2]$
 - Solve system of $K+1$ equations:

$$\begin{pmatrix} E[f] \\ E[Sf] \\ E[S^2 f] \\ \vdots \\ E[S^K f] \end{pmatrix} = \begin{pmatrix} 1 & E[S] & E[S^2] & \dots & E[S^K] \\ E[S] & E[S^2] & E[S^3] & & \\ E[S^2] & E[S^3] & E[S^4] & & \\ \vdots & & & \ddots & \\ E[S^K] & & \dots & & E[S^{2K}] \end{pmatrix} \begin{pmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_K \end{pmatrix}$$

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Approximation - Polynomials

- Optimal solution:

$$\begin{pmatrix} a_0^* \\ a_1^* \\ a_2^* \\ \vdots \\ a_K^* \end{pmatrix} = \begin{pmatrix} 1 & E[S] & E[S^2] & \dots & E[S^K] \\ E[S] & E[S^2] & E[S^3] & & \\ E[S^2] & E[S^3] & E[S^4] & & \\ \vdots & & & \ddots & \\ E[S^K] & & \dots & & E[S^{2K}] \end{pmatrix}^{-1} \begin{pmatrix} E[f] \\ E[Sf] \\ E[S^2 f] \\ \vdots \\ E[S^K f] \end{pmatrix}$$

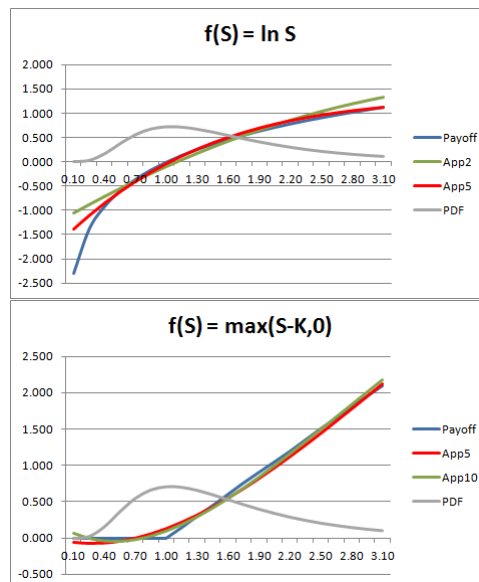
- This is a least squares solution: $a^* = (X'X)^{-1}(X'f)$
 - Implement this estimator for a finite sample
 - Each column in X is S^k
 - Each row in X and f is a draw from the random variable S

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Approximation - Example

- Examples of approximation of payoffs with polynomials
 - Works very well for smooth functions
 - Payoff with kink is difficult for polynomials
- Lesson: choose appropriate basis for payoff



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Approximation - Theory

- The collection of polynomials $1, S, S^2, \dots$ forms a *basis* for the space of payoff functions
- Every function (with $E[f^2] < \infty$) can be perfectly replicated with polynomials for $K \rightarrow \infty$
- Every function f has a unique representation: $f(S) = \sum_{k=0}^{\infty} a_k S^k$
- The coefficients a_k are deterministic (do not depend on S)
- Therefore we can compute (any measure Q and time t):

$$\mathbf{E}^Q[f(S) | F_t] = \mathbf{E}^Q \left[\sum_{k=0}^{\infty} a_k S^k | F_t \right] = \sum_{k=0}^{\infty} a_k \mathbf{E}^Q[S^k | F_t]$$

- Express price of complicated payoff as sum of simple payoffs.

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Approximation - Practice

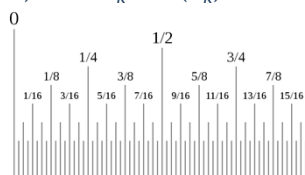
- In practice we can only approximate a complicated $f(S)$ with a finite number of terms: $f(S) \approx \sum_{k=0}^K a_k S^k$
- We can only use a finite sample to estimate the a_k coefficients: $f(S) \approx \sum_{k=0}^K \hat{a}_k S^k$
- Two sources of error:
 - *Truncation error* due to finite K , e.g. converge as $O(K^{-3})$
 - *Estimation error* due to estimate for a_k on sample of size N
 - Study of converge $(K,N) \rightarrow \infty$ by Beutner-Pelsser-Schweizer (2015)
- Choice of different basis will determine convergence rate g for a class of payoff functions
 - Polynomials work very well for smooth functions
 - Polynomials converge slow for kinked payoffs

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Approximation - Choice of Basis

- There are many possible choices for basis-functions
 - Polynomials
 - Sin(), Cos() functions (Fourier basis)
 - Piecewise linear: $\max(S - K_k, 0)$ with $K_k = P^{-1}(d_k)$
 - With d_k are dyadic rationals



- Other, see “machine learning” literature
- Find “good” basis to approximate payoff $f(S)$ with a few basis functions
 - Also compute analytical price for each basis function
 - Piecewise linear \Leftrightarrow call/put options.

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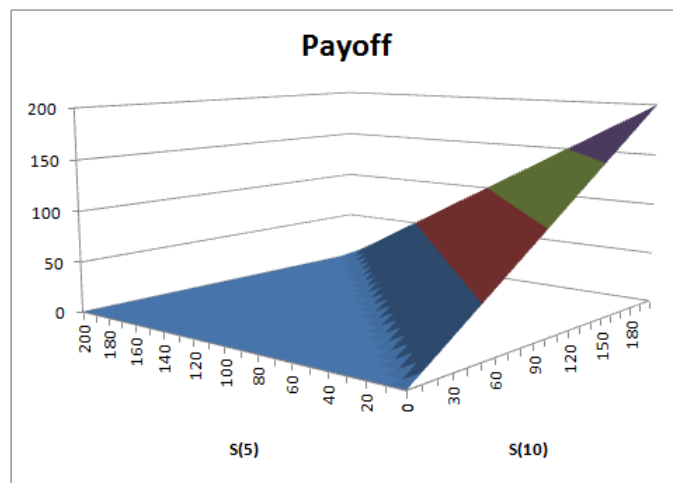
Approximation in Higher Dimensions

Higher Dimensions

- Realistic insurance products have a payoff that depends on multiple risk drivers
- Same risk driver at different points in time
 - Path dependent payoff, such as profit-sharing
- Different risk drivers
 - Unit-linked: mortality and financial
 - Interest rates and inflation
- General theory outlined before still works
- Use more elaborate basis to encompass all relevant risks
- Choice of good basis is even more important

Higher dimension - 2d example

- Consider a path-dependent payoff $\max(S_T - S_t, 0)$ with $t < T$
 - Only pay out positive return of S between t and T .



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Higher dimension - 2d basis

- Consider the following basis
- Poly's up to degree 4
- 15 terms in total
- Need cross-terms
 - Uni terms do not form basis!
 - Eur options do not form basis!
- Curse of dimensionality for dim d : truncation error $O(K^{-g/d})$
 - General result for product basis
 - Really important to find "optimal" basis

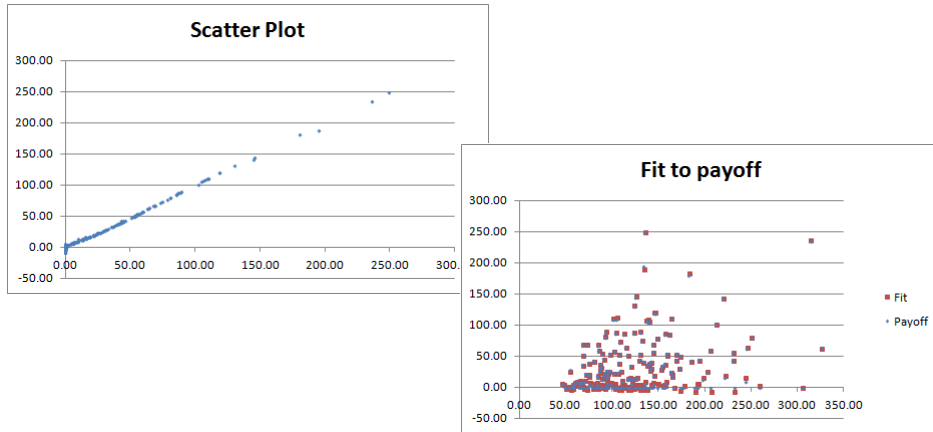
1	S_t	S_t^2	S_t^3	S_t^4
S_T	$S_t S_T$	$S_t^2 S_T$	$S_t^3 S_T$	
S_T^2	$S_t S_T^2$	$S_t^2 S_T^2$		
S_T^3	$S_t S_T^3$			
S_T^4				

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Higher dimension - 2d example

- Draw 200 random values from lognormal process
 - $dS=(4\%)Sdt + (16\%)SdW$
 - Fit payoff $\max(S_{10} - S_5, 0)$ on the 15-term basis

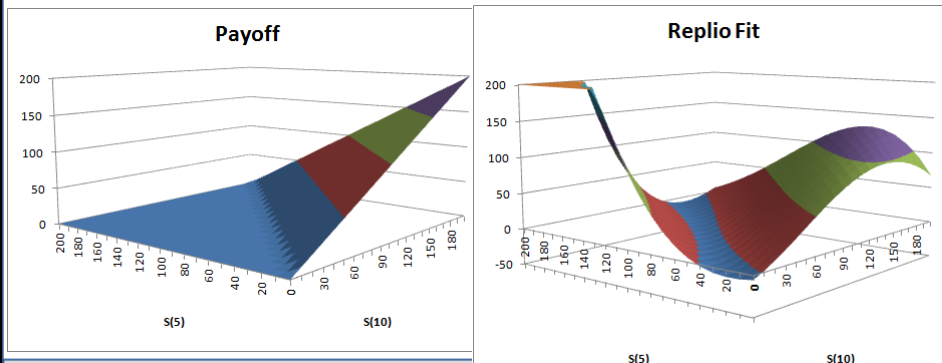


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Higher dimension - 2d example

- Target vs Fitted function
 - Huge errors for S_5 high and S_{10} low...
 - But nearly perfect scatter plot!
- What went wrong?

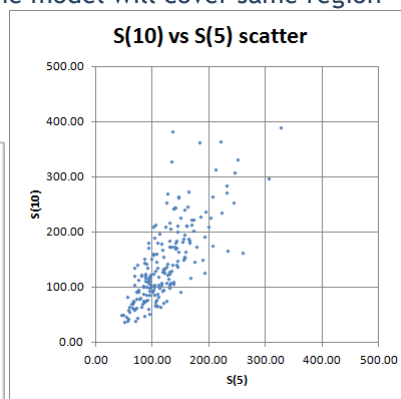
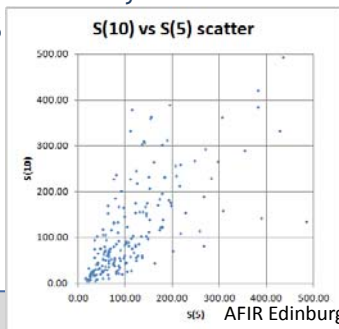


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Higher dimension - 2d example

- What went wrong?
- Realistic training scenarios do not cover the whole space
 - They only cover “realistic” outcomes
 - Out-of-sample simulation from same model will cover same region
- Need to cover whole space
 - Increase volatility in model
 - At 32%

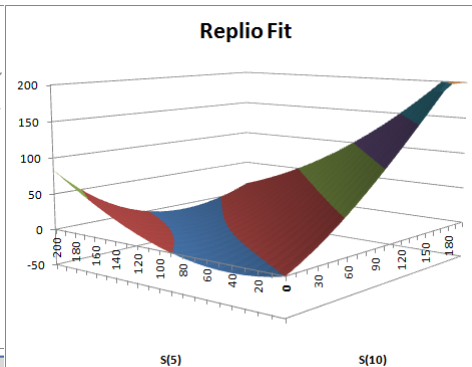
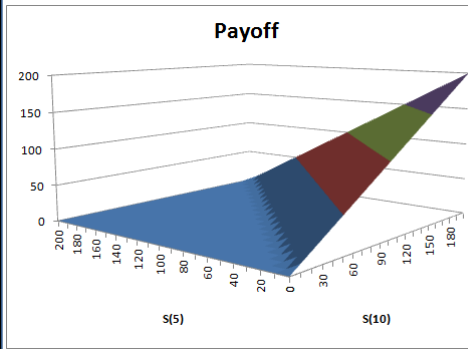


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Higher dimension - 2d example

- Target vs Fitted function
 - Training sample with sig = 32%
- Much improved fit
 - Still errors for S_5 high and S_{10} low



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Higher dimension - Price at t=1

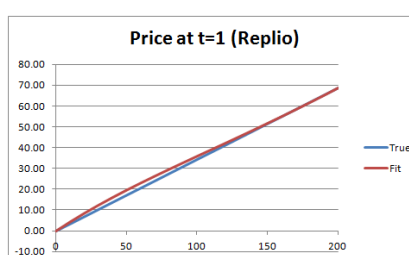
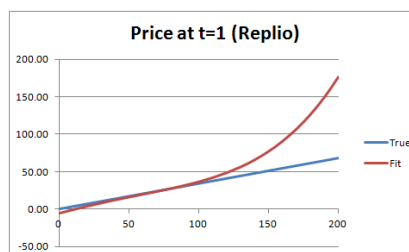
- Calculate price at t=1 of payoff under Q
 - Using realistic training sample

$$\mathbf{E}^Q[\max\{S_{10} - S_5, 0\} | S_1] =$$

$$\sum_{k,l} a_{k,l} \mathbf{E}^Q[S_{10}^k S_5^l | S_1]$$

- Using sig=32% training sample
- Same blue line in both graphs!

- Note: decoupling of training and pricing measure



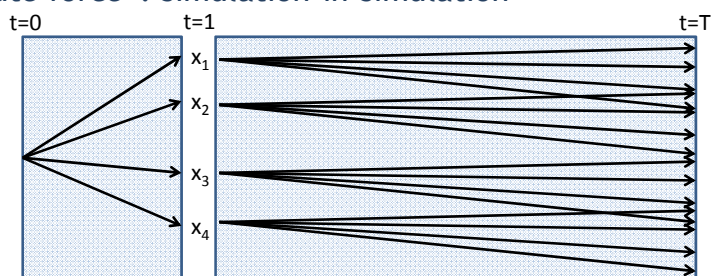
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Replicating Portfolio vs Function Fitting

Calculate prices at t

- Price at t is calculated as conditional expectation under \mathbf{Q} -measure for a specific scenario x at t
 - A scenario is a specific value for the relevant risk-drivers
- Mathematical notation: $\text{price}(t,x) = \mathbf{E}^{\mathbf{Q}}[f(S_T) \mid S_t=x]$
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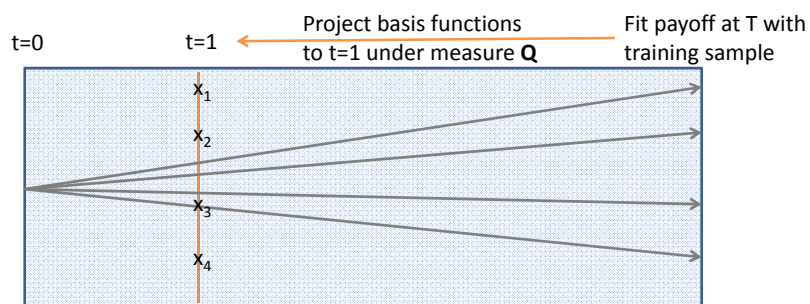
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Calculate price at t

- Alternative methods to calculate prices at t
- **Replicating portfolio:**
 - First fit payoff on basis at T , then calculate expectation at t

$$f(t, S_t) \approx \sum_{k=0}^K \hat{a}_k \mathbf{E}^{\mathbf{Q}}[(S_T)^k \mid F_t] \quad \text{with} \quad \hat{a} = (\mathbf{E}^{\mathbf{R}}[S_T^k S_T^l])^{-1} \cdot \mathbf{E}^{\mathbf{R}}[S_T^k f(T, S_T)]$$



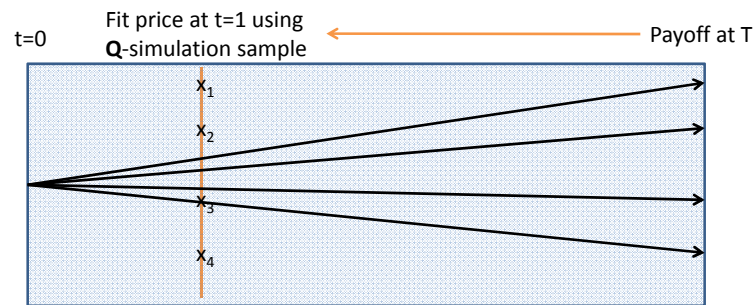
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Calculate price at t

- Alternative methods to calculate prices at t
- **Function fitting:**
 - Calculate price at t by regressing payoff at T on basis at t

$$f(t, S_t) \approx \sum_{k=0}^K \hat{b}_k^Q (S_t)^k \quad \text{with} \quad \hat{b}^Q = (\mathbf{E}^Q[S_t^k S_t^l])^{-1} \cdot \mathbf{E}^Q[S_t^k f(T, S_T)]$$



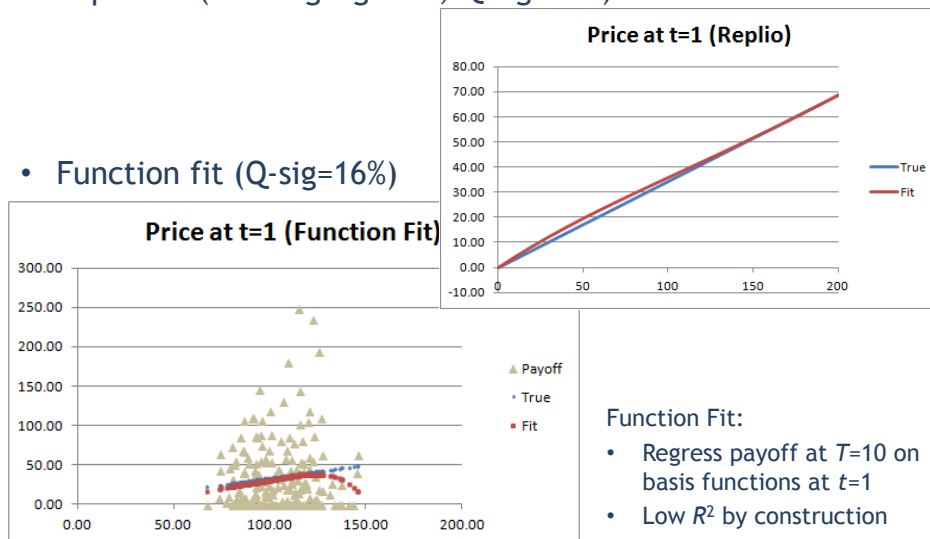
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Example for 2d payoff

- Replio fit (training sig=32%, Q-sig=16%)

- **Function fit (Q-sig=16%)**



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Replicating Portfolio vs Function Fitting

- | | |
|---|---|
| <ul style="list-style-type: none"> • <i>Replicating portfolio / Regress Later</i> • First fits the payoff function • Compute cond.expectation of basis analytically • Harder for path-dep payoff • Test quality of fit • Is model-independent: changing the pricing Q-measure does not affect the coefficients a_k | <ul style="list-style-type: none"> • <i>Function Fitting / LSMC / Regress Now</i> • Directly fits the pricing function • Applies a smoothing during estimation • Easy for path-dep payoff • Cannot test quality of fit • Is model-dependent: calculated price depends on simulated sample under Q-measure |
|---|---|

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