

Towards Machine Learning: AI as an alternative to GLM's for Ratemaking

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Agenda

Overview of Machine Learning

- Introduction to Machine Learning
- Types of Algorithms

Generalized Linear Models

- Poisson Gamma GLM's
- Tweedie Compound-Poisson GLM's

Artificial Neural Networks

- Structure and Architecture
- How ANN's Work and Learn

Applications to Insurance Data

- Fitting models
- · Comparison of Poisson-Gamma GLM, Tweedie GLM and Neural Network on data

Building and Training Neural Networks

Key Takeaways and Conclusions





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Machine Learning

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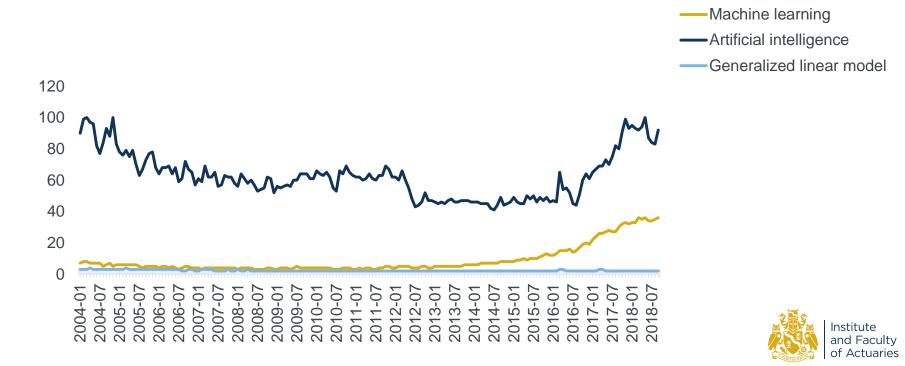
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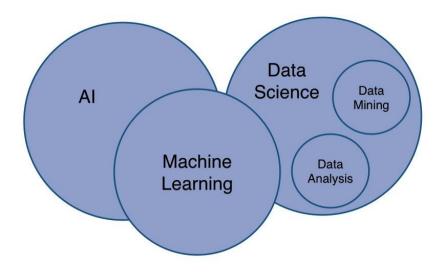
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Machine Learning in Perspective



Machine Learning





Machine Learning



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The "teaching a kid math" analogy



Machine Learning

All about patterns!!!



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All about patterns!!!

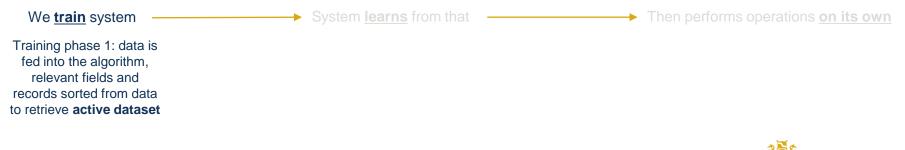
Computer systems <u>learn</u> from data

We <u>train</u> system — System <u>learns</u> from that — Then performs operations <u>on its own</u>



All about patterns!!!

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Computer systems <u>learn</u> from data

We train system

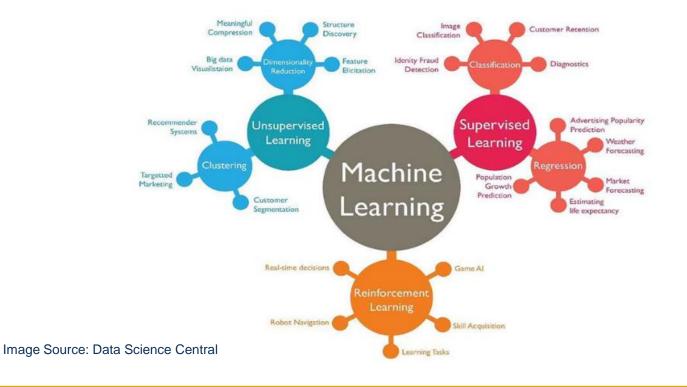
System learns from that

Then performs operations on its own

Testing phase: new data fed into system, algorithm uses patterns & relationships learnt during the training phase to predict new cases



Types of Algorithms







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Generalized Linear Models

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Generalized Linear Models





Components of this model:

- Random component Specifies distribution of target variable
- Systematic component covariates (x's) produce linear predictor (exp.1)
- Systematic component linked to random component $g(\mu) = \eta \rightarrow \textbf{Link Function}$





Poisson-Gamma GLM's

- Claim frequency follows Poisson model with Log link
- Claim severity follows Gamma model with Log link

Expected Risk Premium = Expected Claim Frequency × Expected Claim Severity

Poisson model

Gamma model



Standard GLM's – Random Component comes from Exponential Family

Distribution	Variance
Gaussian	ϕ
Binomial	$\frac{\mu_i(1-\mu_i)}{n_i}$
Poisson	μ_i
Gamma	$\phi \mu_i^2$
Inverse Gaussian	$\phi \mu_i^3$



Tweedie models – Variance has a more general relation with expected value

$$V(\mu) = \mu^p$$

p can take any value and is called the *variance power parameter*



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<u>Compound Poisson</u> -p between 1 and 2



Basic idea behind CP models in Ratemaking

- N_i observed claim count for *ith* category; Z_i observed claim cost for that category (assuming 1 exposure year)
- $N_i \sim \text{Pois}(\lambda_i) \& Z_i \sim \text{Gamma}(\tau_i, \alpha)$
- $Z_i | N_i \sim \text{Gamma w/mean } N_i \tau_i$
- Tweedie approach assumes: $\mu_i = E(Y_i) = \lambda_i \tau_i \& V(Y_i) = \phi \mu_i^p$ where

$$p = \frac{\alpha + 2}{\alpha + 1}$$

- Since $\alpha > 0$, we must have 1
- For 0 claims, distribution approximates to Poisson; for non-zero claims, approximates towards Gamma





• What if claims follow a fit different from Poisson-Gamma?



- What if claims follow a fit different from Poisson-Gamma?
- What if we didn't have to look for a fit at all?



- What if claims follow a fit different from Poisson-Gamma?
- What if we didn't have to look for a fit at all?
- What if there was a way to be able to automate pure premium modelling and potentially find a better fit at the same time?





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Artificial Neural Networks

Making <u>computers</u> think like <u>we</u> do!

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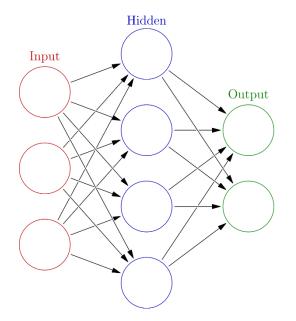
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Artificial Neural Networks

Structured Sequential model



Structured: A Neural Network has a defined structure that consists of 3 types of layers

Sequential: Information flows in a sequence from one layer to the next, undergoing operations at each layer – almost like an assembly line



How ANN's work



How ANN's work

Data in every neuron is transformed by an <u>activation function</u>:

$$h_k(x) = g(\beta_{0k} + \sum_{i=1}^n x_i \beta_{ik})$$

 $h_k(x) - k^{th}$ neuron in a hidden layer β_{ik} - coefficient of the i^{th} previous-layer neuron on above neuron



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Data in every neuron is transformed by an <u>activation function</u>:

$$h_k(x) = g(\beta_{0k} + \sum_{i=1}^n x_i \beta_{ik})$$

 $h_k(x) - k^{tn}$ neuron in a hidden layer β_{ik} - coefficient of the *i*th previous-layer neuron on above neuron

 Activation function transforms the linear combination of inputs from one layer and sends it to the next layer.





• At first, each neuron is randomly assigned a <u>weight</u> – this measures the contribution of that neuron to the next layer.



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- Predictions are compared with actuals based on a loss function.
- Weights are updated to reduce value of loss function.





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$$\nabla_{\rm W} \mathbf{L} = \frac{\delta L}{\delta W}$$

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<u>**Gradient**</u> of the Loss function – measures change in loss function as model weights change

- The above function is computed and a step is taken in the direction where it is minimized the most.
- Size of this step is the learning rate.



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- Suppose for Neuron A and iteration t, the weight was found to be $W_{A(t)}$
- Then, for iteration t + 1, weight is optimized to:

$$W_{A(t+1)} = W_{A(t)} - \eta \nabla_{W_{A(t)}} L$$

η – Learning Rate
 ∇_{W_{A(t)}}L – Gradient of Loss Function w.r.t. weight of Neuron A at iteration t



 Vanilla approach: Compute gradient for entire training sample and update weights based on that



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- Vanilla approach: Compute gradient for entire training sample and update weights based on that
 - No method to check if full convergence is achieved
 - What if different parameters work differently and require different optimization rates?
- Stochastic Gradient Descent: Compute gradient for each individual point in the training sample and update weights iteratively for every sample
 - Too slow Might cause algorithm to crash or give up for extremely large datasets, thus
 potentially preventing full convergence



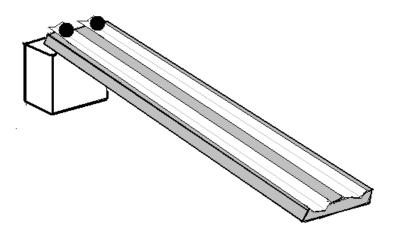
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- Methods such as **Momentum** and the **Nesterov Accelerated Gradient** improve SGD and make it faster by optimizing learning rates internally



Think of it as a ball rolling down a hill



So what's going on here?



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The "teaching a kid math" analogy





• ...make assumptions about distributions



- ...make assumptions about distributions
- ...worry about possible correlations between predictors



- ...make assumptions about distributions
- ...worry about possible correlations between predictors
- ...look for interactions between predictors





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Applications to Insurance Data

dataCar from R's insuranceData package

Data Description

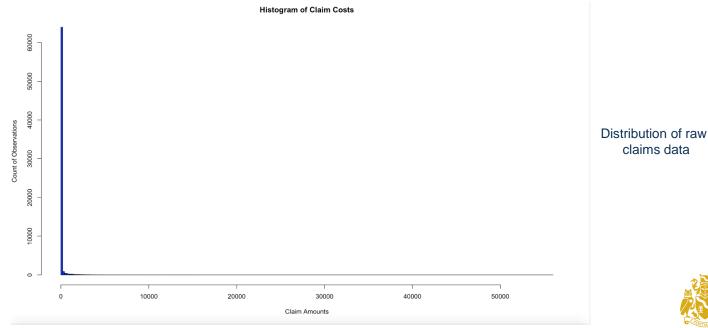
- Policyholder-level information on one-year vehicle insurance policies
- 67,856 records with following rating factors
 - Vehicle value in \$10,000's
 - Vehicle body type (eg. Sedan, convertible, hatchback, bus & other levels)
 - Vehicle age (Levels 1-4 w/1 being the newest & 4 being the oldest)
 - Gender of driver
 - Area
 - Driver age category (Levels 1-6 w/1 being youngest & 6 being oldest)



Data Description

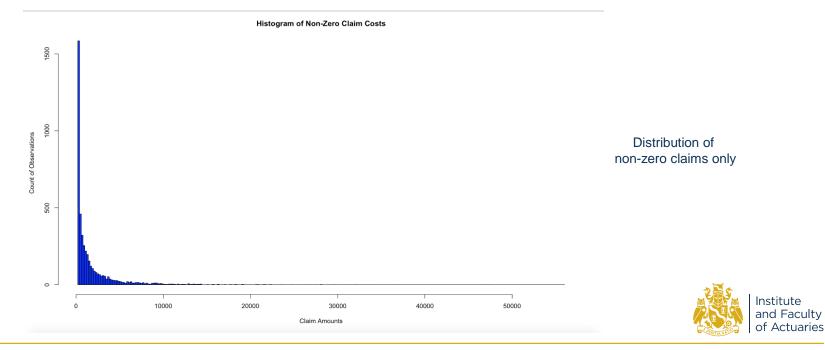


Distribution of Claims

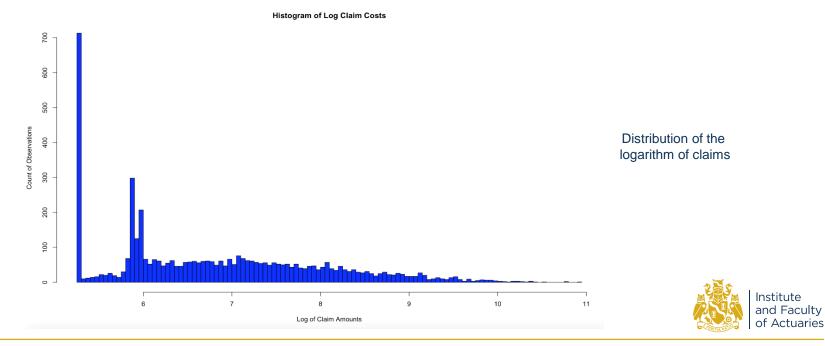




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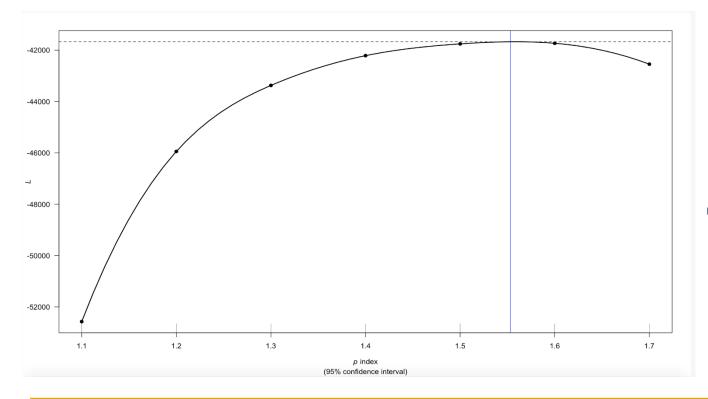


Fitting Tweedie CP GLM

- Optimal variance power parameter tuned by MLE
- Range specified: 1.1 1.9 (all values between 1 & 2)
- Optimal value found to be 1.553



Fitting Tweedie CP GLM



Plot of log-likelihood values against *p* – values. Vertical blue line shows point of maximum likelihood, justifying choice of parameter





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- Base network architectures were trained with the same set of hyperparameters chosen at random



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- Architectures chosen: (33-40-1), (33-80-1), (33-100-1), (33-120-1), (33-80-40-1), (33-100-60-1), (33-120-60-1)



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- Base network architectures were trained with the same set of hyperparameters chosen at random
- Architectures chosen: (33-40-1), (33-80-1), (33-100-1), (33-120-1), (33-80-40-1), (33-100-60-1), (33-120-60-1)
- Best network architecture found to be (33-120-60-1) this was chosen for further tuning
- In general, networks with 2 hidden layers fitted better than networks with 1 hidden layer



Fitting Neural Networks – Choosing Hyperparameters



Fitting Neural Networks – Choosing Hyperparameters

- Learning rate and batch size tuned on architecture chosen from previous step
- Tuning done by 5-fold cross-validation
- Following values were chosen to be tested:
 - Learning rate 0.001, 0.01, 0.05, 0.1
 - Batch size 3000, 8000, 10000



Fitting Neural Networks – Choosing Hyperparameters

- Learning rate and batch size tuned on architecture chosen from previous step
- Tuning done by 5-fold cross-validation
- Following values were chosen to be tested:
 - Learning rate 0.001, 0.01, 0.05, 0.1
 - Batch size 3000, 8000, 10000
- Best hyperparameters found to be
 - Learning rate 0.1
 - Batch size 3000



Model Comparison



Model Comparison

- 3 approaches taken
 - Test data predictive accuracy Test RMSE
 - Resampling Error on Training dataset 5-fold Cross Validation MSE
 - Goodness-of-fit test AIC





Model	Test RMSE (× 10 ³)
Poisson-Gamma GLM	1.25
Tweedie Compound Poisson GLM	1.25
Artificial Neural Network	1.27



5-Fold Cross-Validation Error

Model	CV MSE
Poisson-Gamma GLM	1.69×10^{6}
Tweedie Compound Poisson GLM	1.70×10^{6}
Artificial Neural Network	19.98
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- Stands for Akaike Information Criterion
- Gives a measure of distance between true and predicted trends



Model	AIC (× 10 ⁵)
Poisson-Gamma GLM	5.72
Tweedie Compound Poisson GLM	5.73
Artificial Neural Network	5.73
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Building and Training Neural Networks TensorFlow in R



TensorFlow



TensorFlow

- Developed by Google Brain
- Released in 2015





TensorFlow

- Developed by Google Brain
- Released in 2015
- Can be implemented in
 - Python: TF, Keras
 - R: Keras, Estimator, TF API





Building Neural Networks

• Surprisingly easy to build neural networks in R using Keras



Building Neural Networks

- Surprisingly easy to build neural networks in R using Keras
- Models initialized as sequential objects and layers added as nested commands



Building Neural Networks

- Surprisingly easy to build neural networks in R using Keras
- Models initialized as sequential objects and layers added as nested commands
- Once model is constructed, it can be called on a dataset



Model Initialization

Layer definition -

•

Compilation & Fitting

•



Model Initialization

An empty neural network is initialized using *keras_model_sequential()*: Layers can then be added sequentially to the model Layer definition -

•

Compilation & Fitting

•



Model Initialization

Layer definition

Compilation & Fitting

Hidden layers are added and their structure is defined using the command *layer_dense()*: Activation function, # of neurons specified



Model Initialization

Layer definition

►

Compilation & Fitting

►

After model architecture is fixed, hyperparameters, optimizer and loss function are set and using the command *compile()*. Following this, model is trained using the command *fit()*.



Try it out!!!





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Key Takeaways & Conclusions

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AI: The Good and the Not-so-good



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- The Good:
 - Allows for complete automation
 - No need to assume anything about the data, both in terms of rating factors and claim distributions



AI: The Good and the Not-so-good

- The Good:
 - Allows for complete automation
 - No need to assume anything about the data, both in terms of rating factors and claim distributions
- The Not-so-good:
 - Computationally intensive requires hardware such as GPU's and fast/powerful processors to run efficiently
 - Interpretability





- Machine Learning and AI are powerful tools, can aid actuaries in decisionmaking
- Al should definitely be explored and experimented with in addition to using GLM's



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- No one "right" model best predictions can come from ensemble models



- Machine Learning and AI are powerful tools, can aid actuaries in decisionmaking
- Al should definitely be explored and experimented with in addition to using GLM's
- No one "right" model best predictions can come from ensemble models
- Further research being done to improve interpretability of AI, applications of Machine Learning in the actuarial realm



Selected References & Suggested Reading

- Fox, J., Applied Regression Analysis & Generalized Linear Models (Third Edition), Sage Publications, 2016
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- Rumelhart, D. E., Hinton, G. E., Williams, R. J., *Learning representations by back-propagating errors, in Nature Vol. 323*, October 1986
- TensorFlow: <u>www.tensorflow.org</u>
- The R Interface to Keras: <u>https://keras.rstudio.com/</u>
- Léon Bottou, Large-Scale Machine Learning with Stochastic Gradient Descent: http://khalilghorbal.info/assets/spa/papers/ML_GradDescent.pdf





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