

The Actuarial Profession

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GIRO Convention

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Robotic reserving

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Overview

▪ Robotic loss reserving

▪ What is it?

▪ Why is it of interest?

▪ Requirements of a robot

▪ Main components of the robot

▪ Robot supervision

▪ Future development

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Robotic loss reserving – what is it?

▪ P&C loss reserving

▪ Estimation of liabilities for incurred but incomplete claims

▪ Central estimate (i.e. mean value)

▪ Stochastic properties (statistical distribution of the amount of liability)

▪ **Robotic** (or **adaptive**) loss reserving

▪ Software that will produce this output over a sequence of valuation dates

▪ Without human intervention

▪ With no significant loss of accuracy due to lack of intervention

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Robotic loss reserving – why is it of interest?

- Valuation revolving door
 - Many insurers now wish to conduct frequent liability valuations
 - e.g. quarterly
 - They may have 50 or more lines and sub-lines of business recognised for valuation purposes
 - These require separate identification of valuation liabilities because of structurally different models of the claim process
 - These may have many segments
 - State, distribution channel, etc
 - These require separate identification of valuation liabilities for management and/or strategic reasons, e.g. profit measurement
 - These requirements mean that the performance of a quarterly valuation can take about 3 months
 - One valuation ends, another begins

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Robotic loss reserving – why is it of interest?

- Valuation revolving door
 - Obvious advantages in automating such quarterly valuations
 - Once an insurer contemplates a move to monthly valuations, conventional actuarial valuation ceases to be feasible at all
 - A robot is the only option

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Reserving by means of roll-forwards?

- Rolling a valuation forward
 - Consider the case of full half-yearly valuations
 - Roll these forward to provide intermediate monthly valuations
 - Assume that each half-yearly valuation remains valid over the following 5 months
- Value of liabilities at any one of these months =
 Value at previous half-yearly valuation
 less claims paid since then
 plus allowance for claims incurred since then
- Problem here is that the monthly series of loss reserves tends to run smoothly for 5-month periods with 6-monthly shocks
 - Roll-forwards not reliable

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Requirements of a robot

Requirements of a robot

- Must recognise changes in its environment
 - e.g. door is now closed instead of open as it was a minute ago
- Must be able to respond appropriately to these changes
 - e.g. don't attempt to pass through doorway without first taking action to open the door

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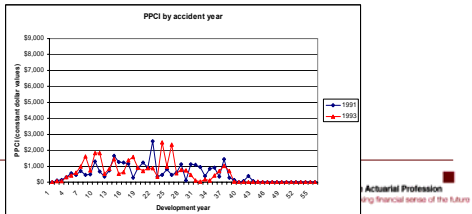
Requirements of a **loss reserving** robot

- Must recognise changes in its environment, e.g.
 - The amplitude of the payment pattern tending to increase with increasing accident period

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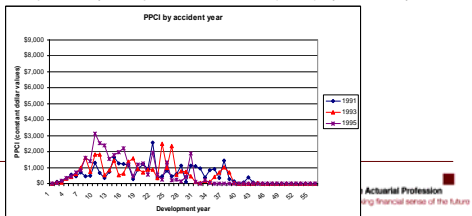
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- Must recognise changes in its environment, e.g.
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 - example of Payment per Claim Incurred (PPCI) by accident year



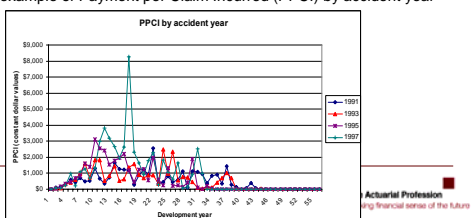
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- Must recognise changes in its environment, e.g.
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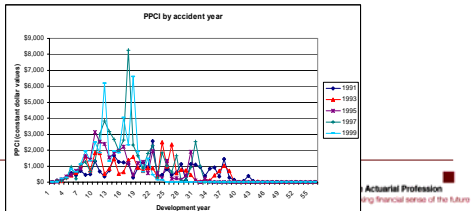
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Requirements of a **loss reserving** robot

- Must recognise changes in its environment, e.g.
 - The amplitude of the payment pattern tending to increase with increasing accident period
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Requirements of a **loss reserving** robot

- Must recognise changes in its environment, e.g.
 - The tail of the payment pattern tending to extend with increasing accident period
 - Case estimates tending to develop more rapidly in more recent accident periods
- Must be able to respond appropriately to these changes
 - Model of claim process must evolve over time to reflect these changes

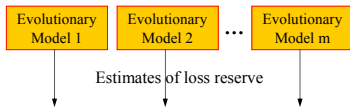
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Robot design

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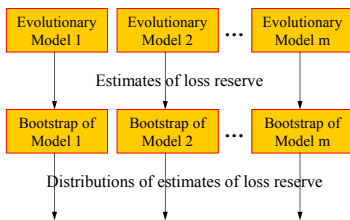
Main components of the robot



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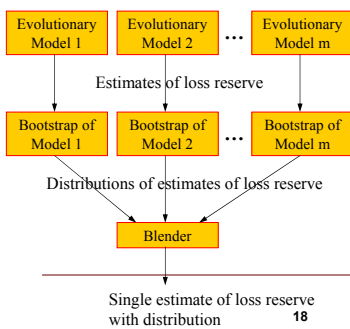
Main components of the robot



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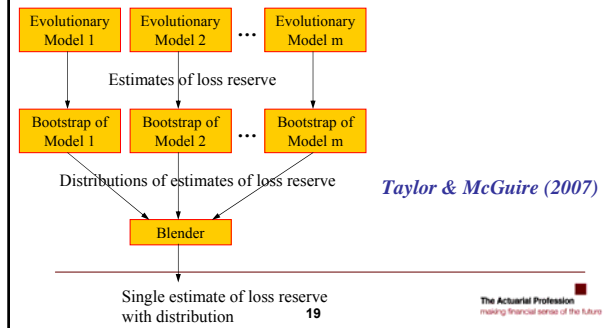
Main components of the robot



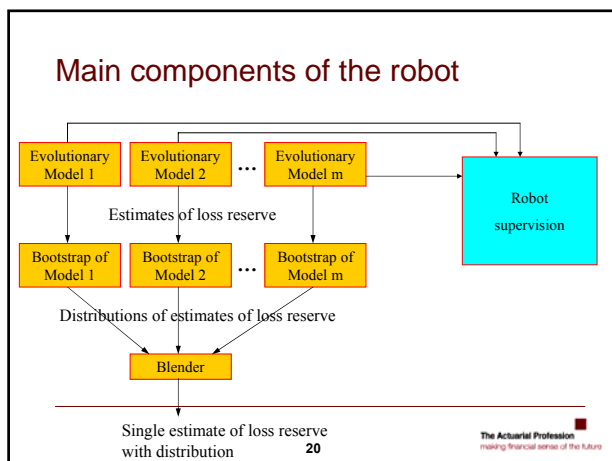
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Main components of the robot



Main components of the robot



Evolutionary models

- These are **Dynamic Generalised Linear Models (DGLMs)**
- Model form is:

$$y_t = h^{-1}(X_t \beta_t) + \varepsilon_t \quad [\text{GLM for period } t]$$

Data vector Link function Design matrix Parameter vector Centred stochastic error

Evolutionary models

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- Model form is:

$$y_t = h^{-1}(X_t \beta_t) + \varepsilon_t \quad [\text{GLM for period } t]$$

Data vector \rightarrow Link function \rightarrow Design matrix \rightarrow Parameter vector \rightarrow Centred stochastic error

$$\beta_{t+1} = G_t \beta_t + \eta_t \quad [\text{parameter evolution}]$$

Matrix \rightarrow Centred stochastic perturbation

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Evolutionary models

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$$y_t = h^{-1}(X_t \beta_t) + \varepsilon_t \quad [\text{GLM for period } t]$$

Data vector \rightarrow Link function \rightarrow Design matrix \rightarrow Parameter vector \rightarrow Centred stochastic error

e.g. row of a run-off triangle

$$\beta_{t+1} = G_t \beta_t + \eta_t \quad [\text{parameter evolution}]$$

Matrix (identity in our case) \rightarrow Centred stochastic perturbation

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Forecasts

- Forecast of y_{t+1} by means of **adaptive filter**
 - Hence "**adaptive reserving**"
- Notation: let

$$Y_{t|s} = E(Y_t | \text{data from } 0, 1, \dots, s)$$

- Estimate

$$Y_{t|t} = Y_{t|t-1} + K_t \{y_t - Y_{t|t-1}\}$$

Gain matrix \rightarrow Realised value of Y_t

or (depending on link function and error terms)

$$Y_{t|t} = Y_{t|t-1} + K_t \{[\text{DIAG } Y_{t|t-1}]^{-1} y_t - 1\}$$

Adaptive filter

- This is a second order approximation to Bayesian updating of the parameter vector β_t (Taylor, 2008)
- It holds for following cases

h	ε	η
identity	normal	normal
log	Poisson	gamma
log	gamma	gamma

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Adaptive filter

- This is a second order approximation to Bayesian updating of the parameter vector β_t (Taylor, 2008)
- It holds for following cases

Kalman
filter

h	ε	η
identity	normal	normal
log	Poisson	gamma
log	gamma	gamma

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Adaptive filter (cont'd)

- Proceed in 3 stages updating 1-step-ahead forecast from $Y_{t|t-1}$ to $Y_{t+1|t}$
 - Update $Y_{t|t-1} \rightarrow Y_{t|t}$ as just illustrated
 - Also update $\text{Var}[Y_{t|t-1}] \rightarrow \text{Var}[Y_{t|t}]$
 - Extract updated parameter estimate $\beta_{t|t}$

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Adaptive filter (cont'd)

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 - Extract updated parameter estimate $\beta_{t|t}$
 - Update $\beta_{t|t} \rightarrow \beta_{t+1|t}$ by means of formula for assumed parameter evolution (in our case $\beta_{t+1|t} = \beta_{t|t}$)
 - Also update $\text{Var}[\beta_{t|t}] \rightarrow \text{Var}[\beta_{t+1|t}]$

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Adaptive filter (cont'd)

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 - Also update $\text{Var}[\beta_{t|t}] \rightarrow \text{Var}[\beta_{t+1|t}]$
 - Update $Y_{t|t} \rightarrow Y_{t+1|t}$ using $\beta_{t+1|t}$
 - Also update $\text{Var}[Y_{t|t}] \rightarrow \text{Var}[Y_{t+1|t}]$

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Adaptive filter (cont'd)

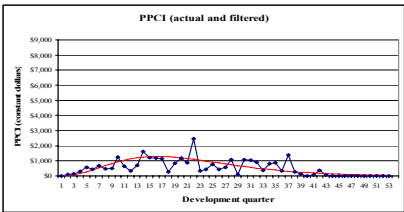
- Proceed in 3 stages updating 1-step-ahead forecast from $Y_{t|t-1}$ to $Y_{t+1|t}$
 - Update $Y_{t|t-1} \rightarrow Y_{t|t}$ as just illustrated
 - Also update $\text{Var}[Y_{t|t-1}] \rightarrow \text{Var}[Y_{t|t}]$
 - Extract updated parameter estimate $\beta_{t|t}$
 - Update $\beta_{t|t} \rightarrow \beta_{t+1|t}$ by means of formula for assumed parameter evolution (in our case $\beta_{t+1|t} = \beta_{t|t}$)
 - Also update $\text{Var}[\beta_{t|t}] \rightarrow \text{Var}[\beta_{t+1|t}]$
 - Update $Y_{t|t} \rightarrow Y_{t+1|t}$ using $\beta_{t+1|t}$
 - Also update $\text{Var}[Y_{t|t}] \rightarrow \text{Var}[Y_{t+1|t}]$
 - Iterate

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Adaptive filter - examples

Data from earlier examples

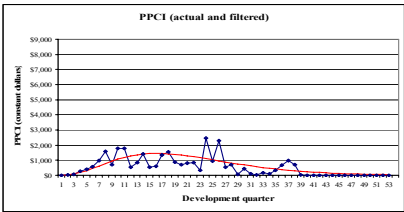


Accident year 1991

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Adaptive filter - examples

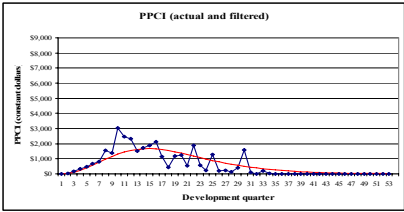


Accident year 1993

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Adaptive filter - examples

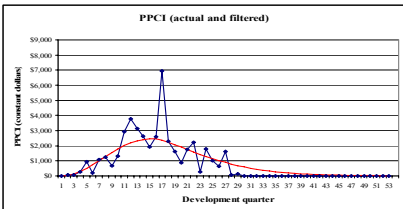


Accident year 1995

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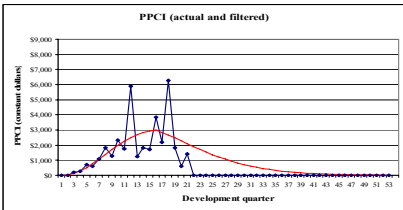
Adaptive filter - examples



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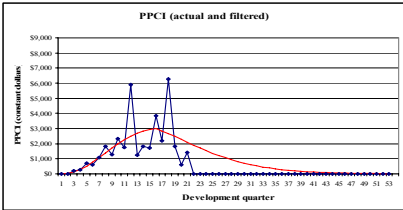
Adaptive filter - examples



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Adaptive filter - examples



N.B. filter
has been
applied to
accident
periods

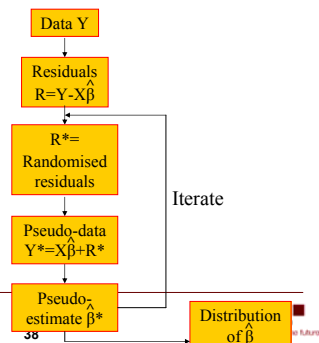
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Bootstrapping

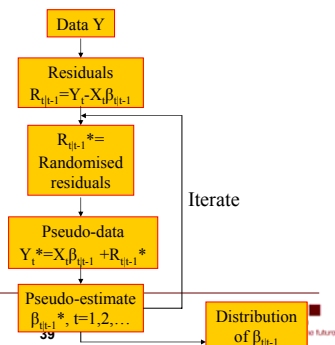
Bootstrapping a filter

- Recall standard form of bootstrap for regression model



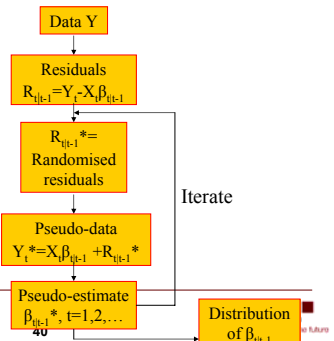
Bootstrapping a filter

- Recall standard form of bootstrap for regression model (adapted to filter)



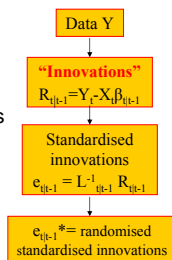
Bootstrapping a filter

- Recall standard form of bootstrap for regression model (adapted to filter)
- Problem here is that bootstrap assumes components of residual vector R are independent
- For a filter
 - $R_{t|t-1} = Y_t - X_t \beta_{t|t-1}$
 - The components of $R_{t|t-1}$ are **NOT** independent because $\beta_{t|t-1}$ has been calculated from $R_{t-1|t-2}, R_{t-2|t-3}, \dots$



Bootstrapping a filter – correct version

- Procedure provided by Stoffer & Wall (1991)
- Let
 - $L_{t|t-1} = \text{Var}[R_{t|t-1}]$
- Standardised innovations are i.i.d.

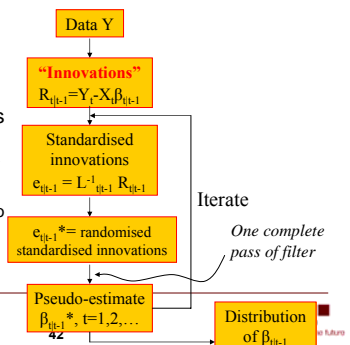


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Bootstrapping a filter – correct version

- Procedure provided by Stoffer & Wall (1991)
- Let
 - $L_{t|t-1} = \text{Var}[R_{t|t-1}]$
- Standardised innovations are i.i.d.
- Note there is no need for pseudo-data
 - Filter is updated from $t-1$ to t using innovations only



Example results of bootstrapping

Using 3 forms of model

PPCI

- Payments per claim incurred
- Payment based

PPCF

- Payments per claim finalised
- Sensitive to the rate of settlement of claims

PCE

- Projected case estimates
- Sensitive to case estimates

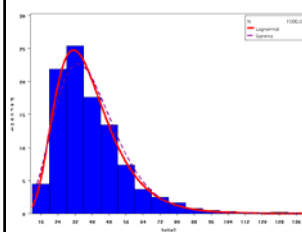
Accident year	PPCI		PPCF		PCE	
	Mean	CV	Mean	CV	Mean	CV
1	8	240%	132	55%	22	105%
2	20	213%	242	47%	56	108%
3	58	169%	165	58%	23	98%
4	110	132%	268	47%	70	90%
5	242	107%	861	30%	317	62%
6	291	74%	1,216	27%	671	64%
7	678	57%	1,257	27%	799	44%
8	817	52%	1,672	27%	1,319	40%
9	2,259	48%	3,366	25%	2,040	32%
10	3,544	48%	3,510	22%	2,368	31%
11	6,366	48%	6,041	21%	5,480	31%
12	7,182	44%	6,742	20%	6,700	31%
13	8,544	43%	8,664	21%	7,234	33%
14	9,001	43%	9,015	21%	3,749	98%
Total ex 14	30,119		34,136		27,099	
Total	39,120	42%	43,151	18%	30,848	22%

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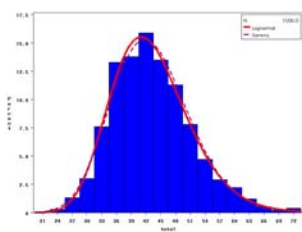
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Example results of bootstrapping

PPCI



PPCF



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Model blending

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Model blending – inputs

- Results after filtering and bootstrapping m models consist of:
 - m sets of estimates of liability by accident year
 - m associated sets of standard errors of prediction
 - Case estimates by accident year

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Model blending

- Let
 $L_i^{(j)}$ = estimated liability for accident year i from model j

- Take final estimates as

$$L_i = \sum_{j=1}^m w_i^{(j)} L_i^{(j)}$$

with

$$\begin{aligned} w_i^{(j)} &\geq 0 \\ \sum_{j=1}^m w_i^{(j)} &= 1 \end{aligned}$$

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Model blending - criteria

- We would like
 - $\text{MSEP}[L]$ to be small where $L = \sum_i L_i$
 - $\sum_i \Delta^2 w_i^{(j)}$ to be small for each j
 - Smooth weights for each model
 - $\sum_i \Delta^2 [\log L_i / C_i]$ to be small where C_i denotes case estimates for accident year i
 - Smooth relation of final estimates to case estimates over accident years

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Model blending – objective function

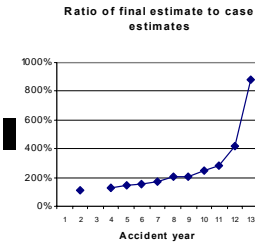
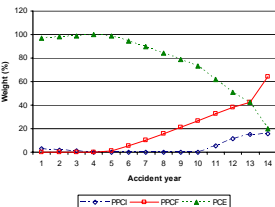
- Problem addressed by Taylor (1985, 2000)
- Minimise the objective function
$$Q = \text{MSEP}[L] + k_1 \sum_j \sum_i \Delta^2 w_i^{(j)} + k_2 \sum_i \Delta^2 [\log L_i/C_i]$$
with respect to the $w_i^{(j)}$, where k_1, k_2 are pre-determined constants that assign weight to the smoothness criteria

Model blending – example of results

Accident year	PPCI		PPCF		PCE		Blended	
	Mean	CV	Mean	CV	Mean	CV	Mean	CV
1	8	240%	132	55%	22	105%	22	104%
2	20	213%	242	47%	56	108%	56	107%
3	58	169%	165	58%	23	98%	24	96%
4	110	132%	268	47%	70	90%	70	90%
5	242	107%	861	30%	317	62%	324	60%
6	291	74%	1,216	27%	671	64%	702	58%
7	678	57%	1,257	27%	799	44%	847	38%
8	817	52%	1,672	27%	1,319	40%	1,375	32%
9	2,259	48%	3,366	25%	2,040	32%	2,317	24%
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11	6,366	48%	6,041	21%	5,480	31%	5,712	20%
12	7,182	44%	6,742	20%	6,700	31%	6,771	18%
13	8,544	43%	8,664	21%	7,234	33%	8,035	17%
14	9,001	43%	9,015	21%	3,749	98%	7,963	20%
Total ex 14	30,119		34,136		27,099		28,927	
Total	30,120	42%	33,151	18%	30,888	22%	36,890	13%

N.B. smaller than for any individual model

Model blending – example of results



Robot supervision

Need for supervision

- Robots affect business bottom line
- Need for strict supervision
- This takes the form of exception reporting
 - Using a range of diagnostics to test whether experience is deviating too far from model predictions

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Example of supervision diagnostics

Accident year	Claim payments in latest period			
	Actual (\$M)	Forecast (\$M)	Actual: forecast	Significance
1991	0.7	1.6	44%	(>10%)
:	:	:	:	:
:	:	:	:	:
2007	25.4	21.0	121%	*** (<1%)
Total	78.7	74.9	105%	* (5-10%)

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Further development

Ample scope for further development

- Filter has been applied to accident periods (rows)
 - Could investigate application to diagonals
 - This could filter superimposed inflation parameters
 - Project currently under way
 - Appears more difficult

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Further development (cont'd)

- Test performance of GLM filter against obvious alternatives
 - MCMC
 - Project currently under way
 - Particle filters
 - Neural nets
 - See e.g. Mulquiney (2006)

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Further development (cont'd)

- Filter applied here to aggregate claim models
- Try application to micro-models (individual claims)
 - Excluding case estimate information (Taylor & McGuire, 2004)
 - Including case estimate information (Taylor, McGuire & Sullivan, 2007)

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Questions?

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